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The Potsdam Open Source Radio Interferometry Tool (PORT)

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Abstract

The Potsdam Open Source Radio Interferometry Tool (PORT) is the very long baseline interferometry (VLBI) analysis software developed and maintained at the GFZ German Research Centre for Geosciences. Chiefly, PORT is tasked with the timely processing of VLBI sessions and post-processing activities supporting the generation of celestial and terrestrial reference frames. In addition, it serves as a framework for research and development within the GFZ's VLBI working group and is part of the tool set employed in educating young researchers. Starting out from VLBI group delays, PORT estimates station and radio sources positions, as well as Earth orientation parameters, tropospheric parameters, and station clock offsets and drifts. The estimation procedures take into account all the necessary data analysis models that were agreed on for contributing to the ITRF2020 processing activities. The PORT code base is implemented in the MATLAB[®] and Python programming languages. It is licensed under the terms of the GNU General Public License and available for download at GFZ's Git server <https://git.gfz-potsdam.de/vlbi-data-analysis/port>.

Unified Astronomy Thesaurus concepts: [Very long baseline interferometry \(1769\)](#); [Astrometry \(80\)](#); [Astronomy data analysis \(1858\)](#)

1. Introduction and Motivation

As one component of the four space geodetic techniques, very long baseline interferometry (VLBI) significantly contributes to our understanding of system Earth (Sovers et al. 1998; Schuh & Behrend 2012; Schuh & Böhm 2013). The retrieval of VLBI data products consists of multiple analysis steps¹² beginning with the raw digitized signal from an extragalactic radio source recorded by the VLBI antennas and leading to the consolidated geodetic and astrometric parameters produced by the International VLBI Service for Geodesy and Astrometry (IVS, Nothnagel et al. 2017) combination center; a

sketch of these analysis steps is shown in Figure 1. Here, we focus on the estimation of geodetic and astrometric parameters based on multi-band group delay observables.

2. Short History of the Software

The development of source code for scientific applications is very often among the tasks of scientists and students but it does not get credited very well unless an article is written about the software itself. The Potsdam Open-Source Radio Interferometry Tool, or short PORT, is the software used and developed for geodetic and astrometric VLBI analyses, scheduling of observations, and simulation of observations by scientists and students that either currently work at GeoForschungszentrum Potsdam (GFZ) or used to work there. Its historical roots go back to the Bonn VLBI Software System (BVSS) developed among others by James Campbell (Campbell 1979) and Harald Schuh (HS) at the Geodetic Institute of the University of Bonn since 1979 (Schuh 1987). This code was then used and further developed

¹² IVS Resolution 2019-02, <https://ivscc.gsfc.nasa.gov/about/resolutions/IVS-Res-2019-02-AnalysisLevels.pdf>.



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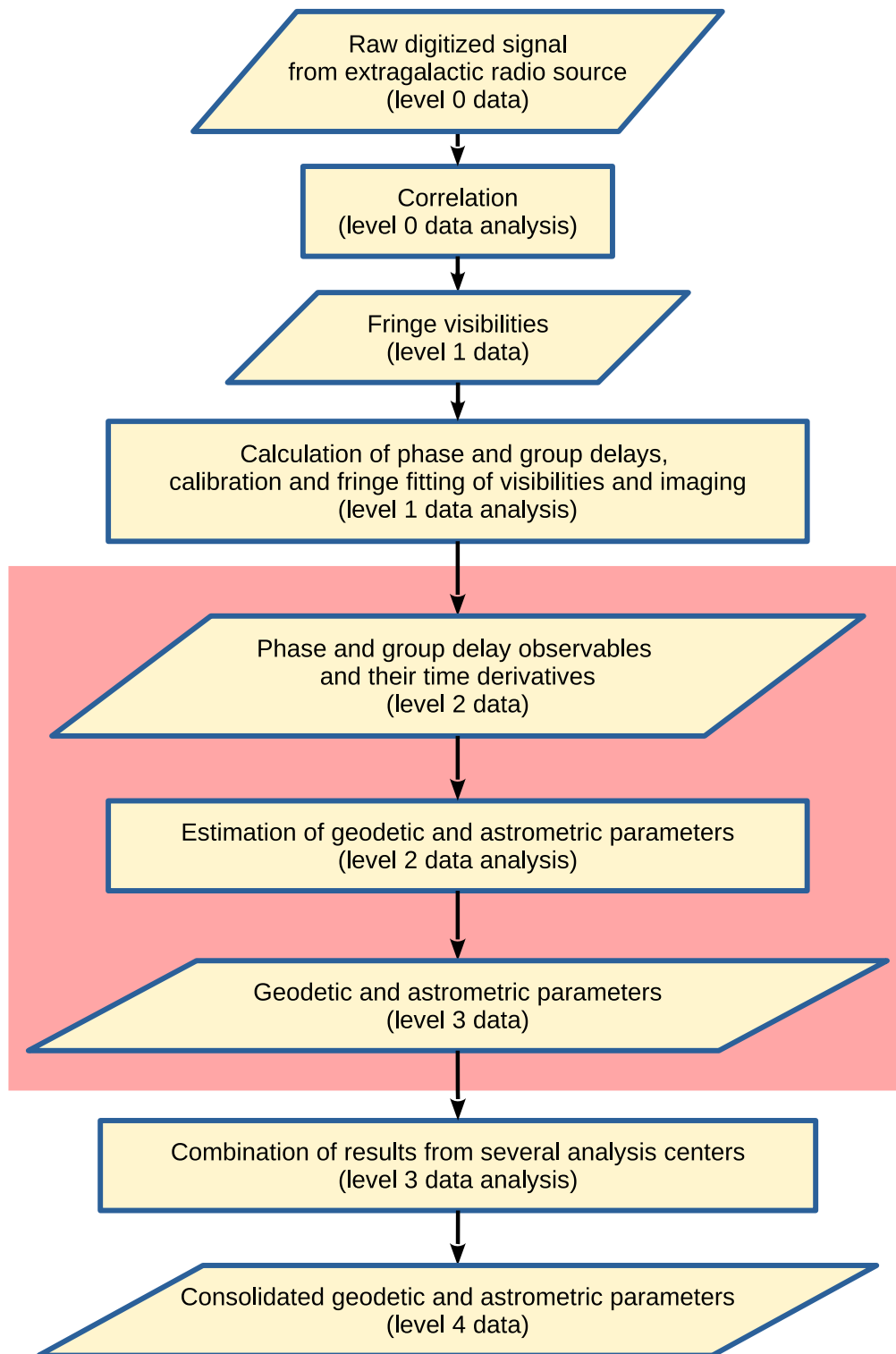


Figure 1. Schematic of VLBI data analysis steps. PORT performs the estimation of geodetic and astrometric parameters from group delay observables (red shaded area, level 2 data analysis).

by other authors, e.g., Nestor Zarraoa (Zarraoa et al. 1990, 1992; Zarraoa 1992) as the basis for the later OCCAM software. Since about 1993, Oleg Titov (Titov & Zarraoa 1997; Titov 2000) was the chairman of the OCCAM VLBI software that was soon used by several groups e.g., in St. Petersburg, Russia and in Munich, Germany. In Munich, OCCAM was further developed by Volker Tesmer and Robert Heinkelmann at Deutsches Geodätisches Forschungsinstitut (DGFI), now DGFI-TUM. Tesmer and Heinkelmann extended in particular the stochastic model in terms of outlier detection and treatment as well as variance component analysis for groups of parameters (Heinkelmann 2002; Kutterer et al. 2003; Tesmer 2004). Additionally, an interface was created between the least squares module of OCCAM and DOGS-CS (DGFI Orbit and Geodetic parameter estimation Software—Combination and Solution) in order to enable the solution of global parameters. At the same time, Titov further developed the Kalman Filter module of OCCAM (Titov et al. 2004). With HS, the VLBI analysis software OCCAM came to Vienna where it was further improved, modernized and finally re-designed in MATLAB[®] (MathWorks[®]) under HS renamed to VieVS (Böhm et al. 2012, 2018). In 2012 when HS left from Vienna University of Technology to GFZ, the VLBI analysis knowledge and software was brought to its current place: Potsdam. In the last several years since 2012 the code was extensively used and edited by a variety of scientists, mainly by Tobias Nilsson (TN), within the VLBI Working Group at GFZ under Harald Schuh and Robert Heinkelmann (RH). With more and more VLBI developers and analysts at different institutes around the world cooperating with the GFZ VLBI Working Group and its software, it became obvious that a higher degree of code organization would be mandatory. That was when PORT was initialized.

A key element of the level 2 VLBI data analysis (Figure 1) is the detection and flagging of outlier observations (see Section 3.4). Since outlier identification by manual inspection contains by nature subjective elements, the VLBI community addresses this issue by employing a collection of analysis tools, which implement diverse algorithms and methods. Thus, any newcomer to this toolset is highly appreciated by the IVS, as it tends to reduce the weights of solutions derived by existing analysis softwares. Key objectives of PORT development focus on

1. the timely processing of VLBI sessions,
2. post-processing activities in support of the realization of terrestrial and celestial reference systems without relying on legacy data analysis packages,
3. supporting the data analyst in interactive tasks through visualization tools and suitable user interfaces,
4. providing tools for observation scheduling and simulation,
5. providing a framework for VLBI research and development projects,
6. applying advanced models, and

7. facilitating the education of young researchers in VLBI data analysis.

Two documents describe in detail the PORT installation procedure and provide recipes on how to analyze IVS data using PORT.¹³ In terms of processing speed, a VLBI analysis software implemented in a fourth generation programming language such as MATLAB[®] is clearly outperformed by any software package written in Fortran or C. Still, with pre-determined outliers, PORT manages to completely process the current total set of about 6500 VLBI sessions in about 40 hr on a current hardware (Intel[®] Xeon[®] Gold 5222 CPU with 16 cores, 264 GByte memory); the processing time increases however by at least a factor of two if outlier detection without preexisting information is activated.

3. Discussion of Processing Stages

The PORT software addresses the level 2 data analysis step of the VLBI data processing pipeline (see Figure 1). It reads in ambiguity-resolved group delay time series, that are calibrated to be approximately free of ionospheric delay effects. PORT estimates station and radio source coordinates, as well as Earth orientation parameters (EOP) and their rates. In addition, zenith delays and horizontal atmospheric gradients at the antenna locations, and instrumental effects such as clock offsets and drifts and baseline clock offsets are determined.

3.1. Input Data

The fundamental input data sources feeding the PORT processing chain (level 2 data analysis) are time series of group delays stored in the vgosDB¹⁴ or legacy NGS¹⁵ data formats. In addition to the delay information, meteorological data, such as temperature, pressure, and relative humidity, provided by sensors at the antenna sites, as well as hardware-related calibration data are included in the vgosDB/NGS file(s). Furthermore, PORT collects a priori EOP time series from the International Earth Rotation and Reference Systems Service (IERS) data archives and calculates reference point displacements at a station site. Atmospheric refraction causes delay and bending, which are considered in PORT as well. Mapping functions and atmospheric parameter models consider both effects at the same time. The a priori zenith delays are calculated using the Saastamoinen refraction model (Petit & Luzum 2010) inserting meteorological data from either in situ observations or from meteorological analysis fields of ECMWF. The a priori horizontal atmospheric gradients are calculated from the APG model (Böhm et al. 2013). Finally, general and session-specific processing options and runtime control variables are initialized from ASCII text files using a PORT-specific data format.

¹³ J. M. Anderson, PORT Installation and PORT IVS Cookbook, Technical reports, Technical University of Berlin, 2020.

¹⁴ J. Gipson (2015, private communication).

¹⁵ NGS Format for VLBI Data Transfer, 1983 October, https://cddis.nasa.gov/archive/reports/formats/ngs_card.format.

If information on outlier data points, stored in a separate ASCII text file, is available, the corresponding observations are flagged and excluded from the subsequent analysis tasks.

Besides the functional code for VLBI data analysis, PORT includes code for operational, administrative and format conversion tasks. Monitoring of the IVS archives for the publication of novel or revised vgosDB/NGS data files is handled by a set of Python scripts. The scripts are intended to run regularly at predefined intervals. If new observations are found, the operator on duty is alerted by e-mail and optionally in terms of SMS messages to analyze the session. The operational processing toolkit of PORT includes a database which holds information on the analysis status of each individual VLBI session.

3.2. Functional Model

Table 1 lists the most relevant components of the functional model. The calculation takes into account ITRF2014 (Altamimi et al. 2016) station and ICRF3 (Charlot et al. 2020) source coordinates (other reference frames may be chosen as well), loading models, atmospheric mapping functions (Dill & Dobsław 2013; Balidakis et al. 2018), and relativistic corrections according to the consensus model (Eubanks 1991; Titov et al. 2011) following the Conventions by the IERS (Petit & Luzum 2010). The JPL solar system ephemerides listed in Table 1 are supported out of the box; ephemerides format-compatible with the JPL ephemerides may be used as well. The observables are assumed to be uncorrelated and semi-empirically determined weights are applied.

In addition, the design matrix entries, consisting of the partial derivatives of the observables with respect to each parameter, are calculated. The derivatives are taken at the parameters' a priori values, since in geodetic VLBI the adjustments are assumed to be less than about 4 mas for radio source coordinates and less than about 2 m for station coordinates and thus the linear approximation of the functional model suffices for the desired accuracy (Eubanks 1991).

3.3. Interactive Analysis Mode I: Review of Auxiliary Information

Before starting with the parameter estimation the user is advised to check the correlator report and auxiliary station-specific information. PORT supports these preprocessing tasks, first, by downloading the correlator report (if it exists) and by storing it in the PORT data directory and, second, by providing plots of meteorological data from sensors at the individual stations as well as phase calibration information recorded during the 24 hr measurement period.

Figures 2 and 3 show examples of these auxiliary data recorded at station ONSALA60 during session 14MAY10XA. Together with the correlator report, these plots are supposed to

Table 1
Models Implemented and Available in PORT

Model	Available Options
Earth orientation parameters	EOP 14 C04 (IAU2000) (Bizouard et al. 2019), EOP 08 C04, EOP 05 C04
Precession, nutation	IAU 2006/2000A (Mathews et al. 2002; Capitaine et al. 2003) (Hilton et al. 2006, 2021)
Solid Earth tides	Mathews et al. (2002)
Ocean tidal loading	FES2004, FES2012, FES2014b EOT11a (Savcenko et al. 2012) TPXO.7.2, TPXO.8, TPXO.9, TPXO.9.2a GOT00.2, GOT4.7, GOT4.10 c (Ray 1999) HAMTIDE (Taguchi et al. 2014) Andersen et al. (2006), Andersen & Scharroo (2011)
Pole tides	IERS (2018), IERS (2015), IERS (2010), IERS (2003)
Ocean pole tides	IERS (2010) Desai (2002)
Atmospheric non-tidal loading	GFZ (Dill & Dobsław 2013), GSFC (Petrov & Boy 2004)
Tropospheric mapping function	PMF (Balidakis et al. 2018), VMF3 (Landskron & Böhm 2018), VMF1 (Böhm et al. 2006)
JPL solar system ephemerides	DE200, DE403, DE405, DE421, DE430t, DE438t, DE440t (Park et al. 2021)
Relativistic corrections	consensus model (Eubanks 1991; Titov et al. 2011)
Galactic aberration correction	Titov & Krásná (2018), MacMillan et al. (2019)

guide the analyst in his/her decisions during the subsequent analysis.

3.4. Parameter Estimation

The parameter estimation process starts by determining the difference between the observed and the modeled delay values—the reduced observation vector. All parameters are realized as linear splines (piecewise linear functions). The reference epoch is the 0:00 UTC within the session (24 hr sessions) or closest to the observation epochs (CONT sessions, intensive sessions) in order to be compatible with other space geodetic techniques parameter epochs, such as the ones from GNSS. The length of the spline segments is constant inside a session for each parameter and can be chosen by the analyst. Depending on the chosen segment length several parameters will be outputted by PORT until the first and the last epoch of the observations are covered within a parameter segment. Occasionally, stations do not observe for some time during a session owing to other commitments, for example, the participation in an Intensive session, unforgiving weather, or technical issues. To avoid the noise increase associated with

Table 2

Parameters Estimated by PORT from a 24 hr Session (Single Session Analysis)

Parameter	Time Step	Absolute Constraint	Relative Constraint
Polar motion (x_p, y_p)	24 hr	10 mas	10^{-4} mas day $^{-1}$
Celestial pole offsets (dX, dY)	24 hr	10 mas	10^{-4} mas day $^{-1}$
UT1/Earth rotation angle	24 hr	10 mas	10^{-4} mas day $^{-1}$
Station positions (x, y, z)		10 cm	
Radio source positions (R.A., decl.)		10^3 mas	
Zenith delays	1 hr		26.4 cm day $^{-1}$
Atmospheric gradients	6 hr	0.5 cm	0.2 cm day $^{-1}$
Station clock offsets	1 hr		24 cm day $^{-1}$
Station clock drifts	1 hr		
Baseline clock offsets			

Note. The time interval applies to both, the absolute and the relative constraints.

setting up unknowns that are not supported by observations, PORT is capable of refraining from doing so.

For each EOP two parameters are estimated as part of the normal equation system, one at the epoch of the first scan, the other at the epoch of the last scan of the session. Thus, PORT allows to output EOP offsets as well as their rates. Optionally, EOP estimation at midnight epochs may be set up to facilitate the comparison with other space geodetic techniques. For clock parameters, 1 hourly segments are chosen. Accordingly, PORT outputs 25 parameters for $(n_{\text{clk}} - 1)$ clocks in the network. One value at 0:00 between day 1 and day 2 and then forward and backward in time every integer hour until no more observation epochs are outside. The associated constraints are added in terms of pseudo-observations either by constraining a parameter to its a priori value with a certain weight (absolute constraint) or by constraining the rate of change of a parameter with a certain weight (relative constraint). If just one adjusted parameter for the entire session is targeted, tight absolute constraints can be applied. Depending on the type of the parameter and its anticipated fluctuation per time, the segment lengths listed in Table 2 are typically applied. In addition, the table lists the corresponding absolute and relative constraints, which have been obtained empirically. For ITRF2020, a set of specific piecewise linear functions intervals for clock and atmospheric delay estimation was used for each session, depending on the observation geometry. For stations with poor observation geometry, fewer knots were set up.

At present, efforts are being made to incorporate VieVS@GFZ's Kalman Filter code (Nilsson et al. 2015; Soja et al. 2015, 2016; Soja 2016) into PORT as well. In the current PORT version the parameters are estimated with least squares adjustment (Koch 1999; Niemeier 2001; Teke et al. 2012). The adjustment is performed in two iterations. The parameters estimated in the first solution are clock polynomials of arbitrary degree (usually not higher than

second) for each station—except for one station. The coefficients of this reference station are defined to be zero and, hence, this clock serves as the reference for the other clocks in the network. The clock adjustments may exceed hundreds of microseconds, in extreme cases even one second. In addition, harmonic clock variations, baseline clock offsets and one zenith delay parameter per station are estimated, their contributions are removed and the final adjustment estimates the remaining parameters including again clock offsets, drifts and drift rates.

In Table 2 the parameters estimated by PORT during single session analysis are listed. Apart from EOP, station positions, radio source coordinates, and tropospheric delay parameters (Balidakis et al. 2018), station clock offsets and drifts may be determined. In addition, PORT estimates baseline clock offsets, constant delays on specific baselines, which absorb instrumental effects (e.g., due to failure of individual frequency channels because of radio-frequency interference) on the corresponding baseline. The complete mathematical model of VLBI data analysis is for example described in Heinkelmann (2008).

3.5. Interactive Analysis Mode II: Monitoring of Residuals and Their Statistics

The estimation results are presented to the analyst in several ways. First, following the approach familiar from the VieVS software package (Böhm et al. 2012, 2018), the residuals \mathbf{v}

$$\mathbf{v} \equiv \mathbf{A} \cdot \mathbf{x} - \mathbf{l} \quad (1)$$

as well as their uncertainties are displayed as time series on screen for visual inspection. Here, \mathbf{A} denotes the design matrix, \mathbf{x} the adjustments for the unknown parameters, and \mathbf{l} the reduced observation vector. The user may choose to restrict the plotted data by selecting individual baselines, stations, or radio sources.

Figures 4 and 5 illustrate the interactive procedure. Initially, the analyst can check the residuals from the first estimation stage (see Section 3.4) for large clock breaks. Representing residuals station-wise allows the user to identify systematic errors related to hardware issues at the selected station. For example, the time series of residuals obtained from the analysis of session 18OCT01XA at station WETTZELL, shown in Figure 4, exhibits a discontinuity of about 1.7×10^9 cm, corresponding to a clock jump of about 55 ms at 58393.6294 MJD (2018 October 2 15:06:20 UTC). Using the mouse pointer a marker (red line) is placed at that time to insert a clock break. Every time a clock break is added at a given station, the coefficients of the affected clock polynomial are estimated anew. After repeating the estimation cycle, the residuals from the final estimation stage are inspected and outlier events are flagged, see Figure 5.

Second, to support the analyst in optimizing station-, baseline-, and/or radio source-based weights or even to removing a particular

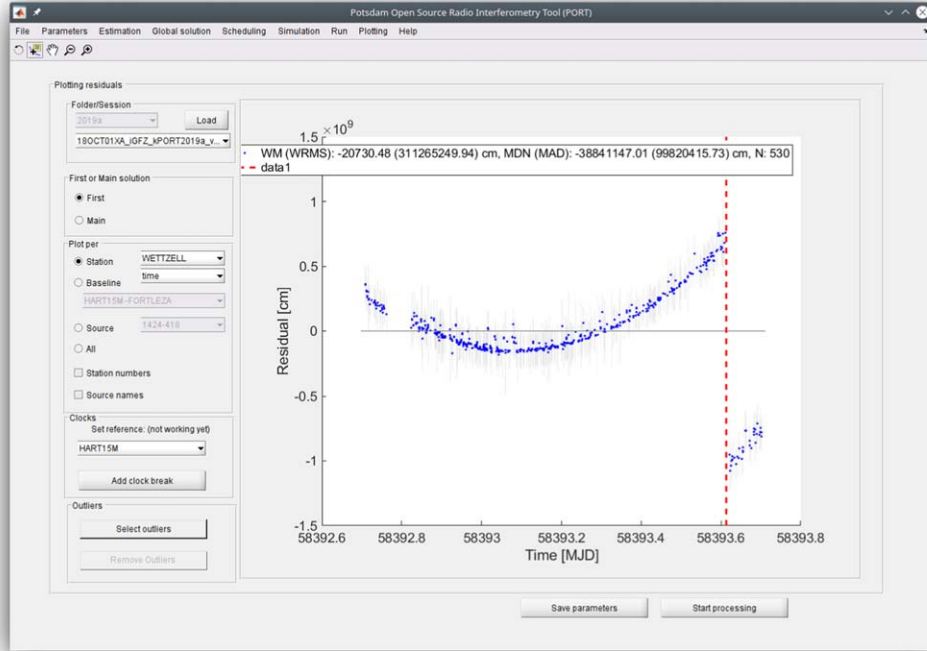


Figure 4. Clock break detection and identification. For the 24 hr session 18OCT01XA the user interface displays residuals for all baselines involving station WETZELL. At 58393.6294 MJD a clock break of about 55 ms is evident (note the units of 10^9 cm (!) for the vertical axis). When flagged by the analyst, the break event is marked by a red line.

station altogether, a table detailing the goodness of the fit (χ^2), the weighted root mean square (rms) residual deviations, the weighted mean values, as well as the (effective) number of observations per station, baseline, and radio source is produced and printed on screen.

Figure 6 displays an example for this type of table obtained as a result of processing session 06MAR23XE using PORT’s current runtime option and processing control settings, denoted as data analysis version “2020b.” These settings include information on, among others, selected models (see Table 1), outlier removal methods, elevation cut-off angles, vgosDB quality control flags, threshold values of the minimum number of stations, sources and/or baselines required, parameterizations of the station clock errors, application of constraints (pseudo-observations), and additional uncertainties to be added to the a priori measurement uncertainties. In the first part the station- and baseline-specific statistics are listed, including the goodness of the fit, in the following denoted “chi-squared” (and also “chi²” in Figure 6),

$$\chi^2 \equiv \frac{\mathbf{v}^T \cdot \mathbf{P} \cdot \mathbf{v}}{n - n_{\text{par}}}, \quad (2)$$

the weighted mean value of the residuals

$$\text{WM} \equiv \langle \mathbf{v} \rangle \equiv \frac{\mathbf{e}^T \cdot \mathbf{P} \cdot \mathbf{v}}{\mathbf{e}^T \cdot \mathbf{P} \cdot \mathbf{e}}, \quad (3)$$

the weighted root mean square of the residuals

$$\text{WRMS} \equiv \sqrt{\frac{\mathbf{v}^T \cdot \mathbf{P} \cdot \mathbf{v}}{\mathbf{e}^T \cdot \mathbf{P} \cdot \mathbf{e}}}, \quad (4)$$

the weighted standard deviation of the residuals

$$\text{WSTD} \equiv \sqrt{\frac{(\mathbf{v} - \langle \mathbf{v} \rangle)^T \cdot \mathbf{P} \cdot (\mathbf{v} - \langle \mathbf{v} \rangle)}{\mathbf{e}^T \cdot \mathbf{P} \cdot \mathbf{e}}}, \quad (5)$$

the effective numbers of observations

$$n_{\text{eff}} \equiv \frac{\mathbf{e}^T \cdot \mathbf{P} \cdot \mathbf{e}}{\max(\mathbf{P})} \quad (6)$$

denoted “n_eff” in Figure 6, and the Student t-distribution (Student 1908), in Figure 6 listed as “t_cdf.” Here, n denotes the actual number of observations (listed as “N” in Figure 6), n_{par} the number of parameters, \mathbf{P} the weight matrix for the observations, $\mathbf{e} \equiv (1, 1, \dots, 1)^T$, and $\max(\mathbf{P})$ is the largest element of \mathbf{P} . These statistics guide the analyst in the decision process which station to down- or up-weight and/or whether baseline clock offsets need to be admitted. In the second part of the table the resulting adjustments for station positions, radio source positions, and Earth orientation parameters are listed.

On the basis of the information described above, the analyst can enter or modify corresponding weights, activate baseline offsets, and remove/deselect stations and/or radio sources. A

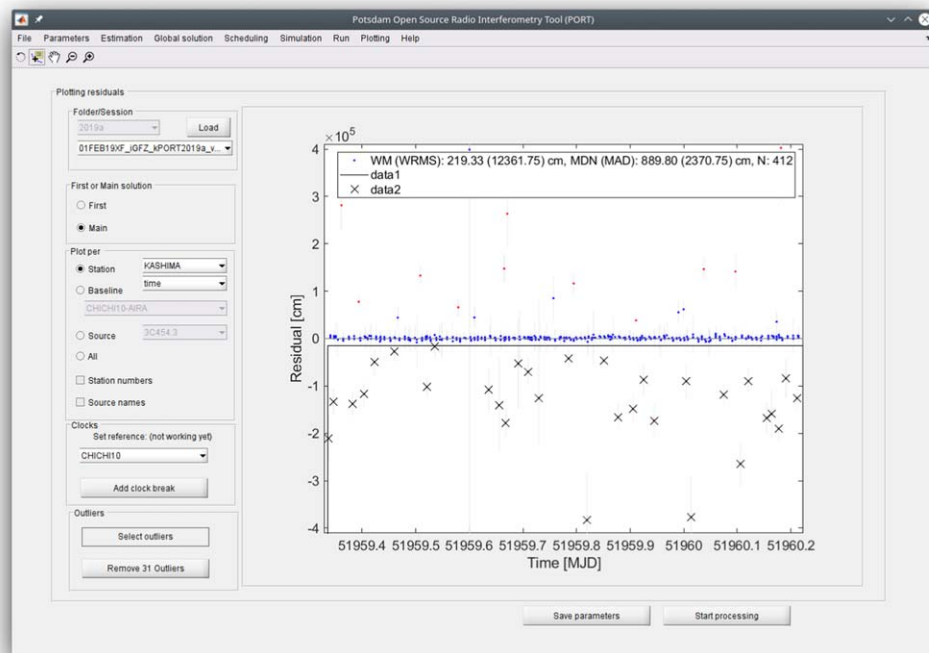


Figure 5. Outlier detection and flagging. During 24 hr session 01FEB19XF a significant number of observations are identified as outlier events. The corresponding data points are selected using the mouse pointer, flagged (marked as crosses in the display) and excluded from the subsequent analysis.

weighted Student t-test triggers a warning message if mean observable residuals at individual stations, baselines, and/or radio sources significantly differ from the value expected on the basis of the null hypothesis and exhibit statistical anomalies (see, e.g., Bevington 1992; Press et al. 1992). Based on this information the estimation/editing/review procedure is iterated until acceptable overall goodness of fit (typically, $0.1 < \chi^2 < 10$) and weighted residual rms values are achieved.

3.6. Automatic Analysis Mode

Besides the interactive mode discussed in Sections 3.3 and 3.5, PORT supports a non-interactive batch mode. Sessions without (or with already known) clock breaks may be processed in this unsupervised automatic mode where outliers are identified using Baarda’s data snooping method, an outlier detection based on statistical tests (Baarda 1967, 1968; Rofatto et al. 2020). For clarity it is emphasized that in automatic mode—just as in interactive mode—PORT estimates parameters and assembles normal equations as well. The speedy analysis of large number of sessions enabled by automatic mode allows for efficient tests and intercomparisons of diverse models (Table 1).

3.7. Output Data

Once the analyst has reviewed the residuals and verified their statistics, the estimated parameters, the a priori information

employed during the estimation procedure, as well as the normal equation systems prepared for the global least squares adjustment are exported, stored in the Solution INdependent EXchange (SINEX) format.¹⁶ Finally, the user has the option to upload the SINEX file to the IVS data servers using a provided Python script. In addition, these data are written to disk in PORT-specific binary file format for subsequent processing. Another set of output files is generated from the selected options and outlier.¹⁷

3.8. Estimation Statistics

Verification and validation of the estimated parameters are an important aspect of geodetic data analysis and one of the key PORT development objectives is to provide the analyst with suitable tools to visualize the results. Furthermore, PORT supports the intercomparison with the analysis results provided by other IVS analysis centers; its quality control tool set allows for the creation of graphical representations of deviations between two or more SINEX-formatted solutions. The comparisons include overall statistics such as goodness of fits and weighted residual rms, and subset statistics of individual EOP variables,

¹⁶ <https://www.iers.org/IIERS/EN/Organization/AnalysisCoordinator/SinexFormat/sinex.html>

¹⁷ J. M. Anderson, PORT IVS Cookbook, Technical report, Technical University of Berlin, 2020.

session	: 2006-03-23-XE (06MAR23XE)								
solution	: 2020b								
chi-squared of main solution (vTPv/degOfFreedom) : 3.2994									
WRMS of residuals : 1.0550 cm									
WRMS of residuals : 35.1902 ps									
Antenna statistics									
Id	antenna	chi^2	WM	WSTD	N	N_eff	1-t_cdf		
1	FORTLEZA	2.7291	-0.0778	1.2387	421	208.1	1.83E-01		
2	MATERA	2.1492	-0.0236	0.9307	660	407.3	3.04E-01		
3	ALGOPARK	1.7934	0.0000	0.8125	539	371.3	5.00E-01		
4	TIGOCONC	1.8333	-0.0517	1.3000	166	64.7	3.75E-01		
5	ZELENCHK	2.9433	0.0000	1.0544	429	276.4	5.00E-01		
6	KOKEE	2.0498	0.0024	1.0567	425	207.1	4.87E-01		
7	SVETLOE	4.8162	0.0046	1.2806	771	544.4	4.67E-01		
8	WETTZELL	2.5434	0.0131	0.9340	787	551.6	3.71E-01		
Baseline statistics									
Ids	baseline	chi^2	WM	WSTD	N	N_eff	1-t_cdf		
1- 2	FORTLEZA - MATERA	1.8543	-0.0390	1.1300	74	36.3	4.18E-01		
	[...]								
7- 8	SVETLOE - WETTZELL	5.4321	0.0215	1.2500	210	175.5	4.10E-01		
	[...]								
adjustment of radio source positions									
Name	Delta_RA	+-	Uncert_RA	Delta_Dec	+-	Uncert_Dec			
	cos(Dec)	+-	cos(Dec)		+-				
	[mas]	+-	[mas]	[mas]	+-	[mas]			
0642+449	0.011	+-	0.209	-0.162	+-	0.188			
			[...]						
2149+056	0.972	+-	0.591	1.269	+-	0.700			
adjustment of antenna station positions (3-d)									
Name	Delta_x	Uncert_x	Delta_y	Uncert_y	Delta_z	Uncert_z	Delta_a	Uncert_a	
	[cm]	[cm]	[cm]	[cm]	[cm]	[cm]	[cm]	[cm]	
FORTLEZA	-0.8379	0.8143	-0.3641	0.8063	-2.1128	0.7363	2.3019	1.3621	
MATERA	0.4517	0.4983	0.1330	0.3517	0.6066	0.5104	0.7679	0.7953	
ALGOPARK	-0.5654	0.3005	0.8287	0.7159	-1.0597	1.1210	1.4593	1.3636	
TIGOCONC	-0.4021	0.7633	0.5094	1.7248	3.2560	2.2188	3.3201	2.9122	
ZELENCHK	0.3435	0.6256	-0.0860	0.6521	-0.0782	0.8309	0.3627	1.2276	
KOKEE	-0.4676	1.0810	-1.8623	0.6092	-1.7250	0.8089	2.5812	1.4812	
SVETLOE	1.1104	0.3194	0.9837	0.4251	0.3904	0.6924	1.5340	0.8730	
WETTZELL	0.3673	0.3429	-0.1426	0.3036	0.7227	0.5389	0.8232	0.7072	
Earth orientation parameters									
Name	Estimate	Uncert	Unit	A_priori	Uncert	Unit	Diff	Uncert	Unit
XPOL	97.290	0.175	mas	97.414	0.000	mas	-0.124	0.175	mas
celestial ephemeris pole, X coord.									
YPOL	377.124	0.288	mas	377.353	0.000	mas	-0.229	0.288	mas
celestial ephemeris pole, Y coord.									
NUTDX	0.198	0.128	mas	-0.028	0.000	mas	0.225	0.128	mas
celestial pole offsets, X coord.									
NUTDY	-0.395	0.121	mas	-0.410	0.000	mas	0.014	0.121	mas
celestial pole offsets, Y coord.									
DUT1	279.136	0.011	ms	279.128	0.000	ms	8.605	10.791	us
UT1 minus UTC									

Figure 6. Estimation results and their statistics obtained from the analysis of 24 hr session 06MAR23XE. Note the change of unit in the last column of “DUT1,” the deviation of UT1 from UTC. For brevity the table has been edited and abridged.

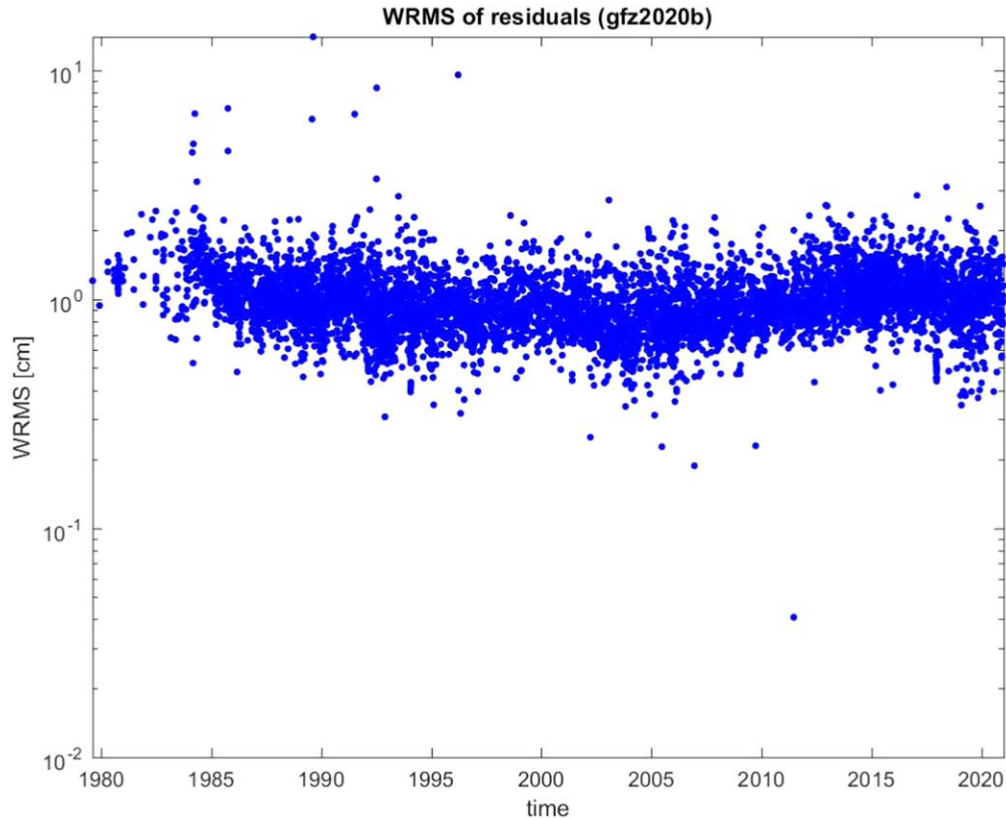


Figure 7. PORT statistics of weighted residual rms as a function of observation time. The results are extracted from SINEX files prepared for GFZ’s VLBI contribution to ITRF2020.

stations, or radio sources. For ease of access the images are displayed through a set of static HTML pages.

Figures 7 and 8 exemplarily illustrate statistical results for GFZ’s VLBI contribution to ITRF2020¹⁸ (K. Balidakis et al. 2021, in preparation). Figure 7 displays the temporal evolution of weighted rms corresponding to the PORT analysis of more than 6500 sessions recorded between 1979 August and 2020 December. The histogram of the deviations between the absolute value of UT1–UTC extracted from PORT’s “gfz2020b” and NASA Goddard’s “gsf2019a” solutions are plotted in Figure 8. While perfect agreement has not yet been achieved, the two data sets appear to be consistent on the 30–100 μ s level.

4. Summary, Conclusions and Outlook

The VLBI analysis software Potsdam Open Source Radio Interferometry Tool (PORT) branched off from the VieVS@GFZ and VieVS tools, which in turn trace their origin to the BVSS and OCCAM software packages. PORT is offered by GFZ German Research Centre for Geosciences as a contribution to the community in order to enhance and extend

the existing selection of well-established analysis packages. Starting from group delays, PORT provides estimates of station positions, radio source positions, Earth orientation parameters, and atmospheric parameters. The estimation procedures support the conventional analysis options for the contribution to ITRF2020 (K. Balidakis et al. 2021, in preparation). The operational analysis itself is preceded by preprocessing tasks performed by a set of Python scripts. PORT performs the level 2 data analysis in two iterations. If outlier and option information already exists, automatic mode processing may be selected; otherwise, the analysis can be performed in interactive mode. Outliers and options are saved to disk, estimation results are stored in SINEX files. The statistics of the overall residuals, as well as the subset belonging to specific stations, baselines, and/or radio sources, are provided to support analyst’s decisions on flagging or reweighting. Quality control tools are provided to compare multi-session data sets. Present development efforts focus on the implementation of ambiguity resolution for phase delays and the incorporation of a Kalman Filter functionality. The design and implementation of data structures, as well as internal and external interfaces of the existing Matlab® code base, are being improved and documented in order to achieve better robustness, modularity

¹⁸ https://ivscc.gsfc.nasa.gov/IVS_AC/IVS-AC_ITRF2020.htm

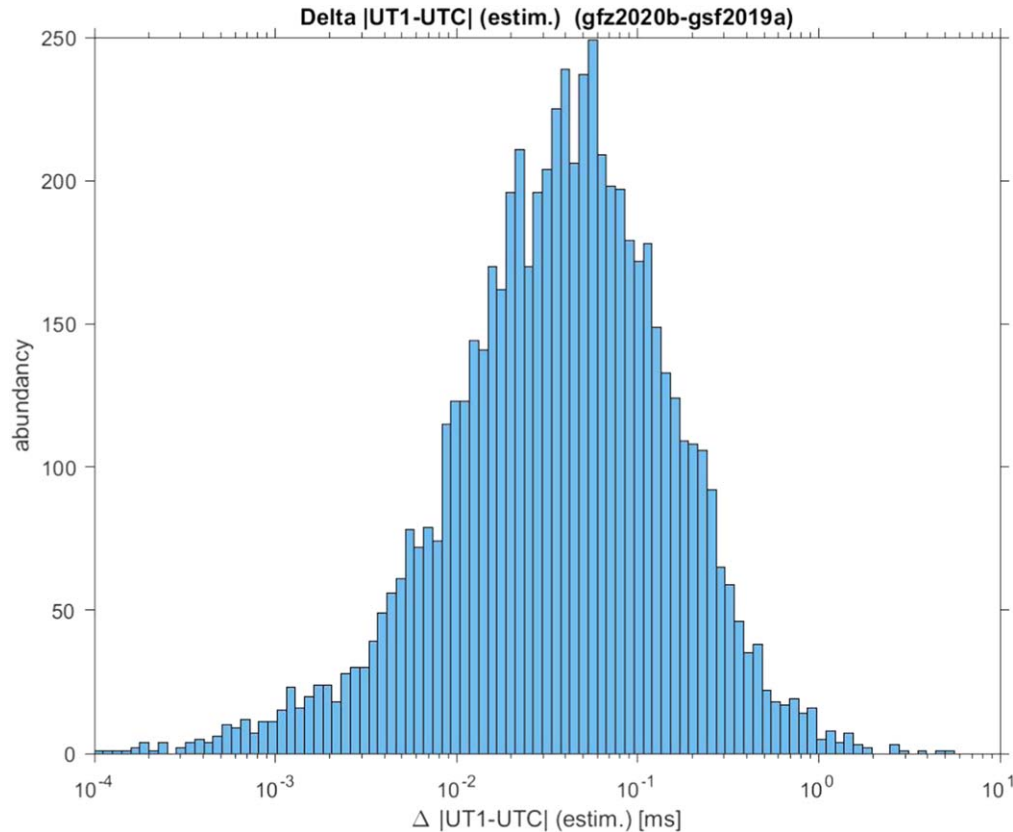


Figure 8. Same as Figure 7, however, showing the histogram of the deviation between $|UT1 - UTC|$ extracted from PORT’s “gfz2020b” and NASA Goddard’s “gsf2019a” solutions.

and execution efficiency. Special emphasis will be placed on utilizing MATLAB®’s advanced visualization capabilities. For PORT system requirements, software availability, and license information see the [Appendix](#).

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Appendix System Requirements, Software Availability, and License

PORT is implemented in the MATLAB® and Python programming languages (MATLAB® release R2021a, version 9.10 or higher, Python version 3.6 or higher). Current development is focused on Linux®-based operating systems. In future Microsoft® Windows® and Apple® macOS® could be supported as well. Users of the PORT software are kindly requested to cite this reference in their publications. The PORT source code is available for download at GFZ’s Git server <https://git.gfz-potsdam.de/vlbi-data-analysis/port> under the GNU general public license.

PORT is free software: you can redistribute it and/or modify it under the terms of the GNU General Public License as published by the Free Software Foundation, either version 3 of the License, or (at your option) any later version.

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