Deep Learning for Post-Processing Ensemble Weather Forecasts

Other Conference Item

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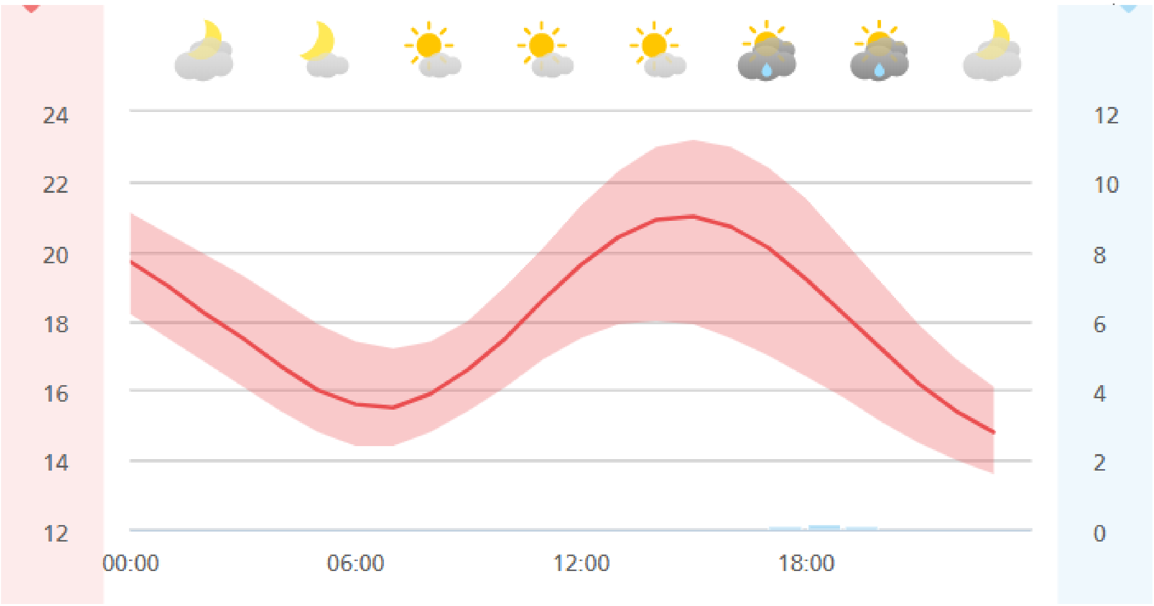
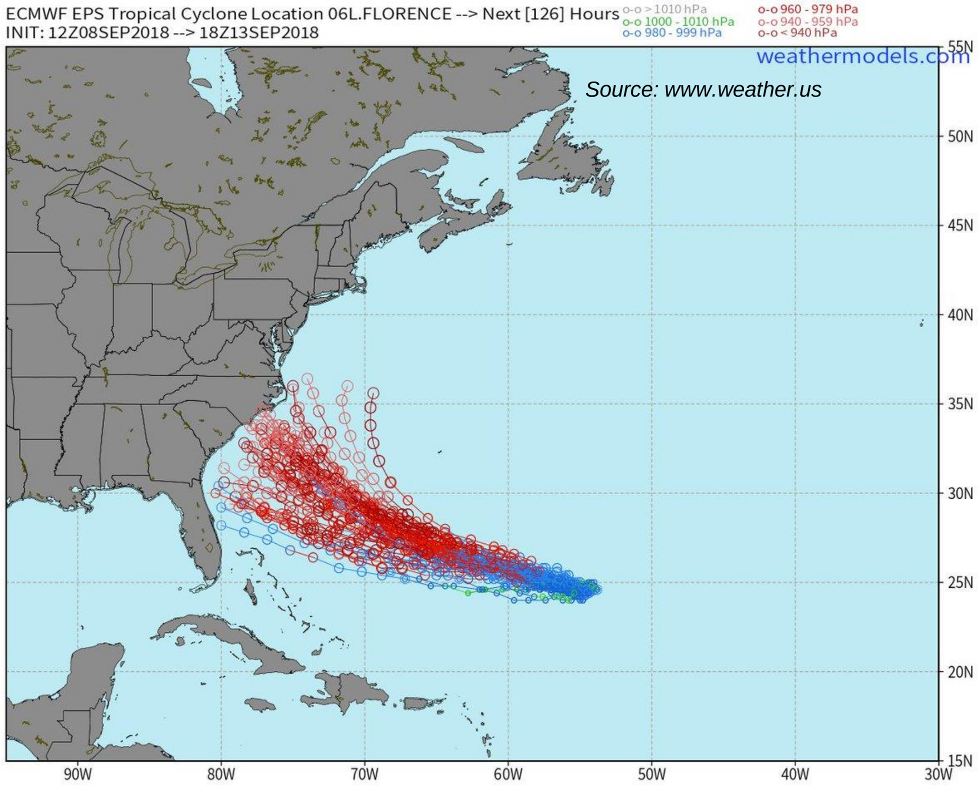
Deep Learning for Post-Processing Ensemble Weather Forecasts

ESIWACE 2020 workshop, virtually anywhere

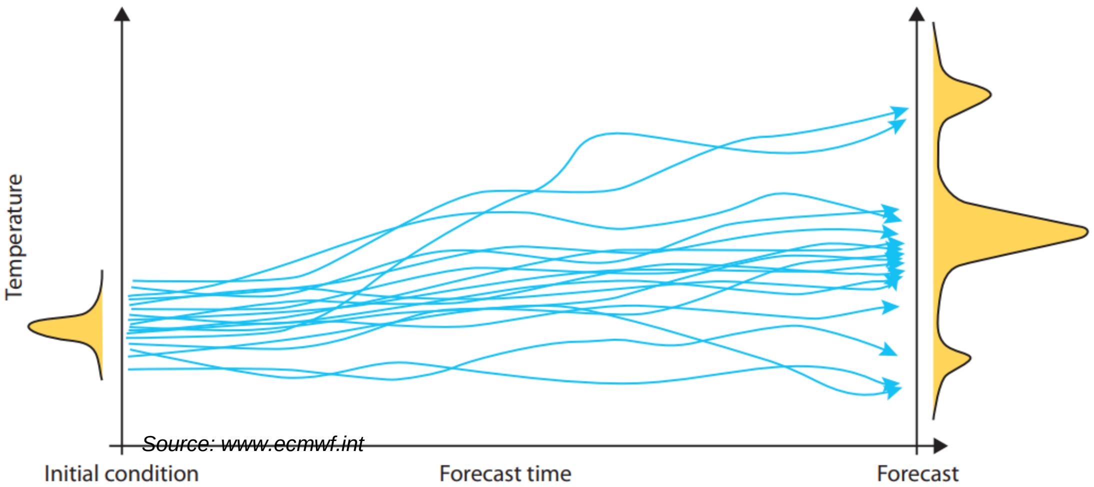
SPCL

Uncertainty in forecasting





- Weather is a chaotic system
  - Minor perturbations affect the outcome the further into the future we predict
- Solution: Ensemble Prediction Systems – predict weather as a probability distribution
  - Approximated by (stochastic) partial differential equations

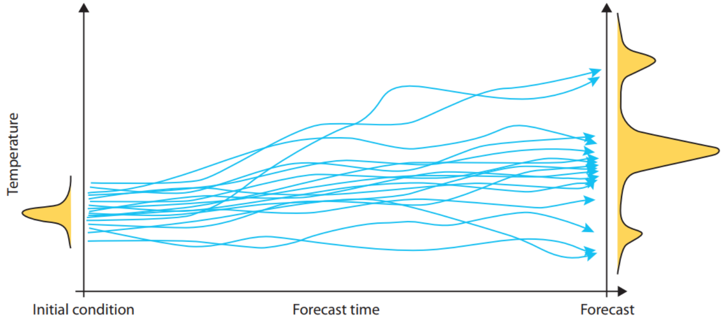


Ensemble Prediction System at ECMWF

- Initial condition uncertainties result from data assimilation

- 51 ensemble members, 1 control (deterministic), 50 perturbed (stochastic)
  - Approximate the highest likely trajectory from output distribution D
  - Lower resolution (9km vs. 18km) in order to fit compute budget

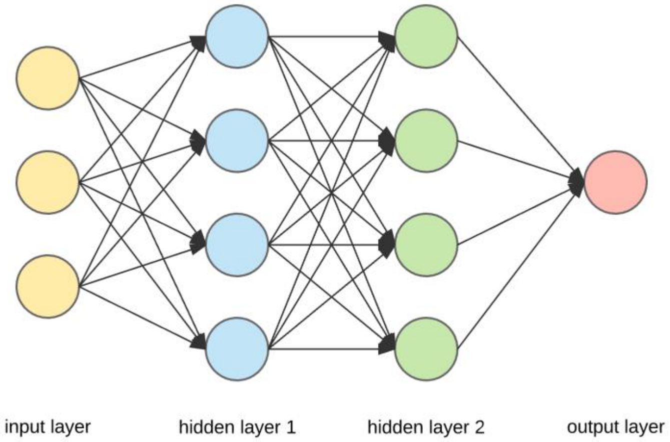
    mostly an economic argument



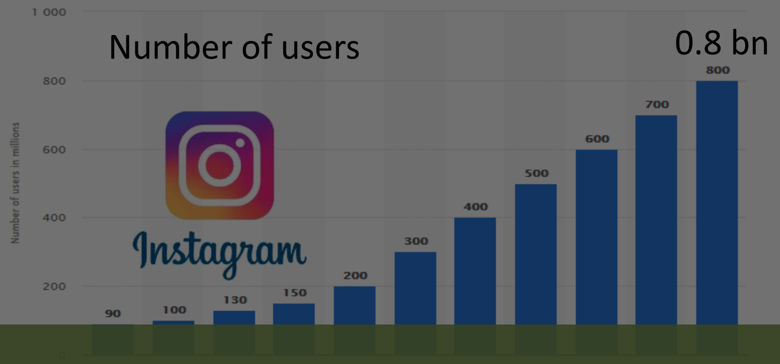
- Next step in the economic argument:
  - Could the number of ensemble members be reduced without sacrificing accuracy?
  - Idea I: predict mean and standard deviation (StdDev) of D from a smaller ensemble

    This may allow us to increase resolution at equal cost – better predictions
  - Can we improve prediction quality by learning from ground truth observations?
  - Idea II: learn (local) model bias from observations

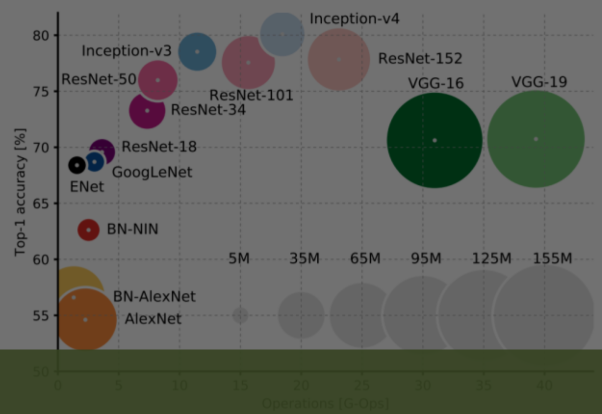
    This may allow us to increase accuracy – better predictions

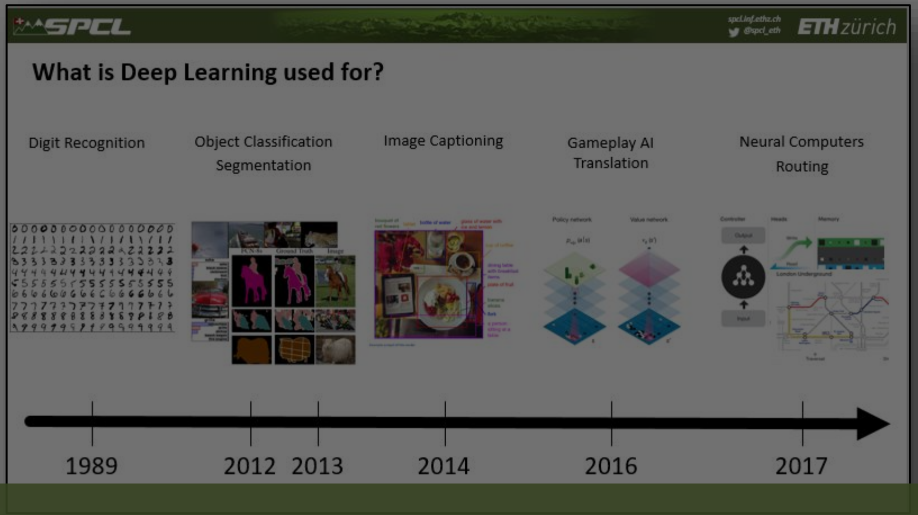


Why machine learning/deep learning?

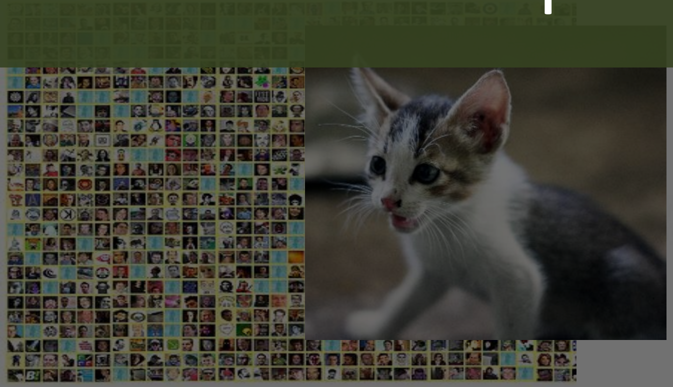


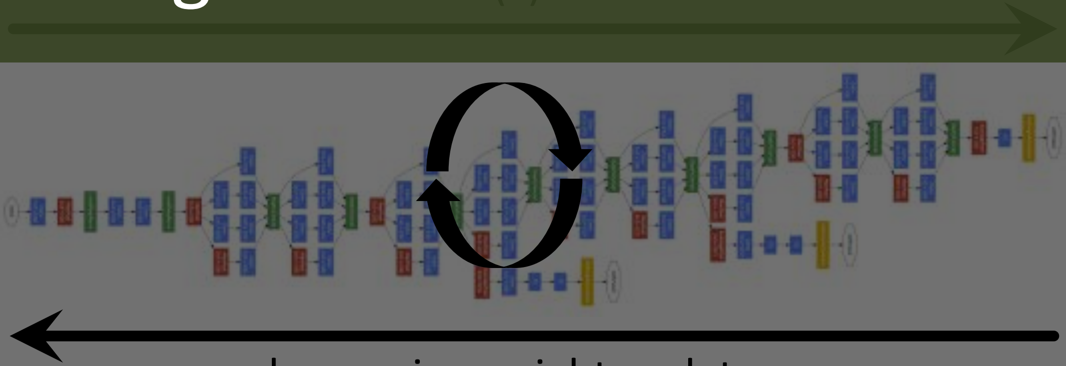
Canziani et al. 2017





Deep learning is a multi billion-dollar industry!





Cat	0.54	Cat	1.00
Dog	0.28	Dog	0.00
Airplane	0.07	Airplane	0.00
Horse	0.04	Horse	0.00
Bicycle	0.33	Bicycle	0.00
Truck	0.02	Truck	0.00

layer-wise weight update

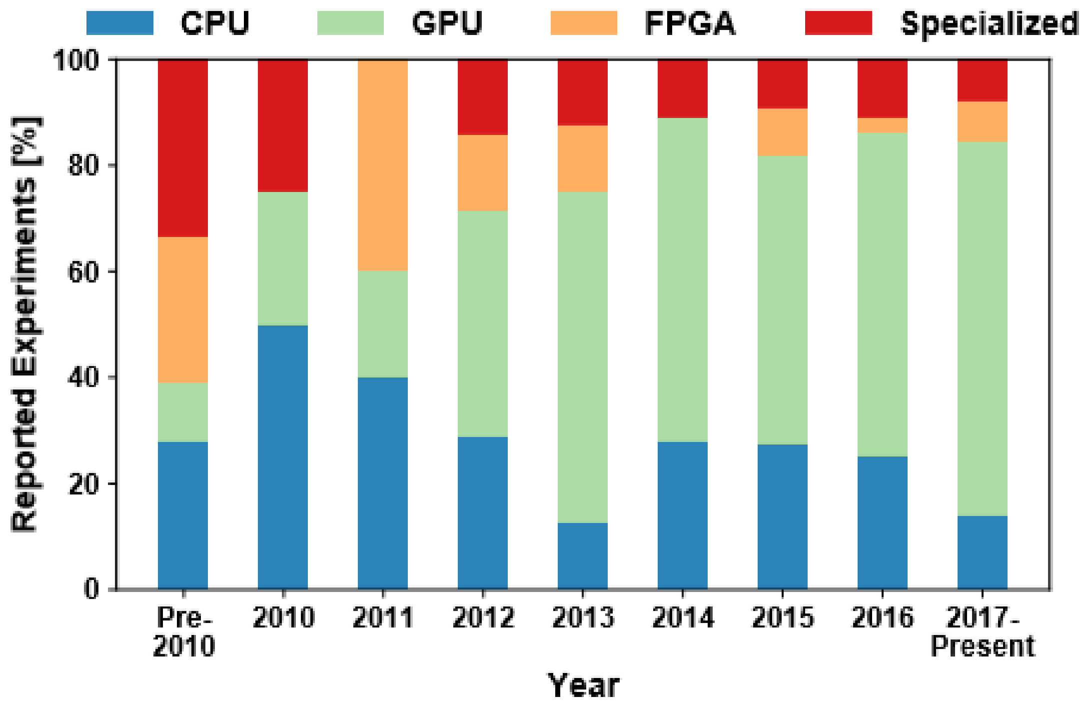
- ImageNet (1k): 180 GB
- ImageNet (22k): A few TB
- Industry: Much larger

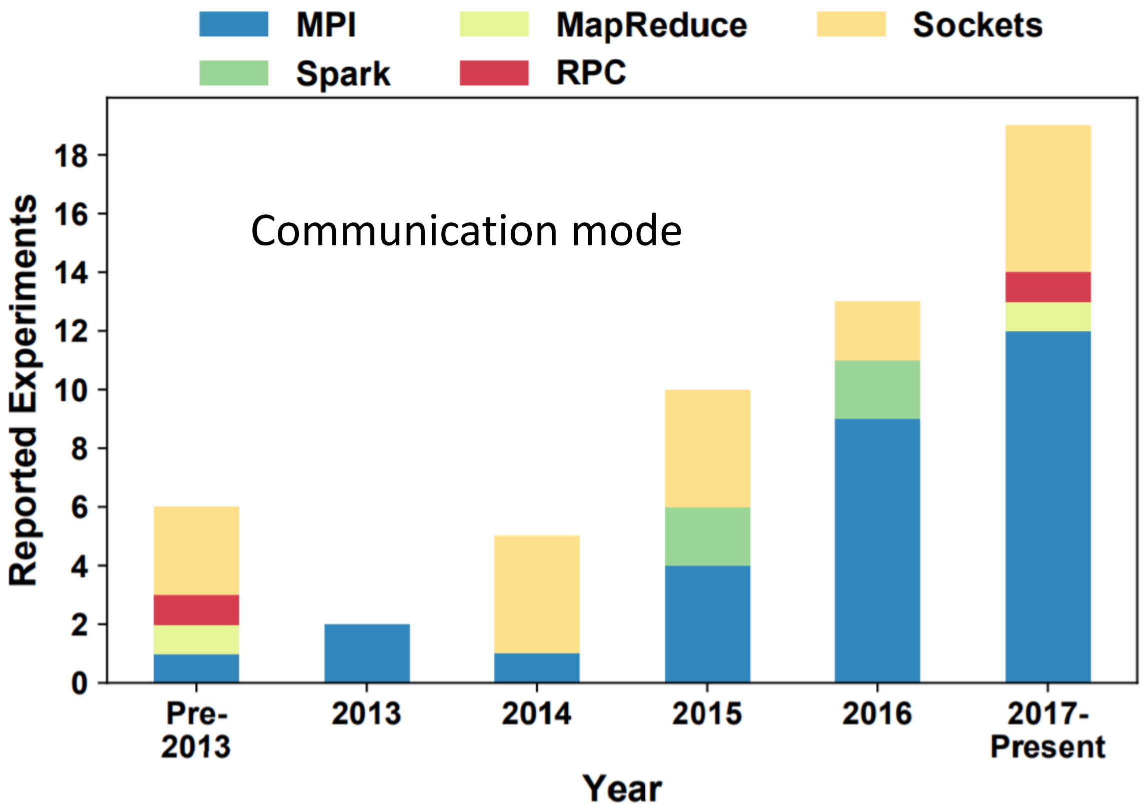
- 100-200 layers deep
- ~100M-2B parameters
- 0.1-8 GiB parameter storage

- 10-22k labels
- growing (e.g., face recognition)
- weeks to train

And everybody is optimizing for it …

The field is moving fast – trying everything imaginable – survey results from 227 papers in the area of parallel deep learning





Deep learning is here to stay – as programming 2.0 or otherwise!

T. Ben-Nun, T. Hoefler: Demystifying Parallel and Distributed Deep Learning: An In-Depth Concurrency Analysis, arXiv Feb 2018

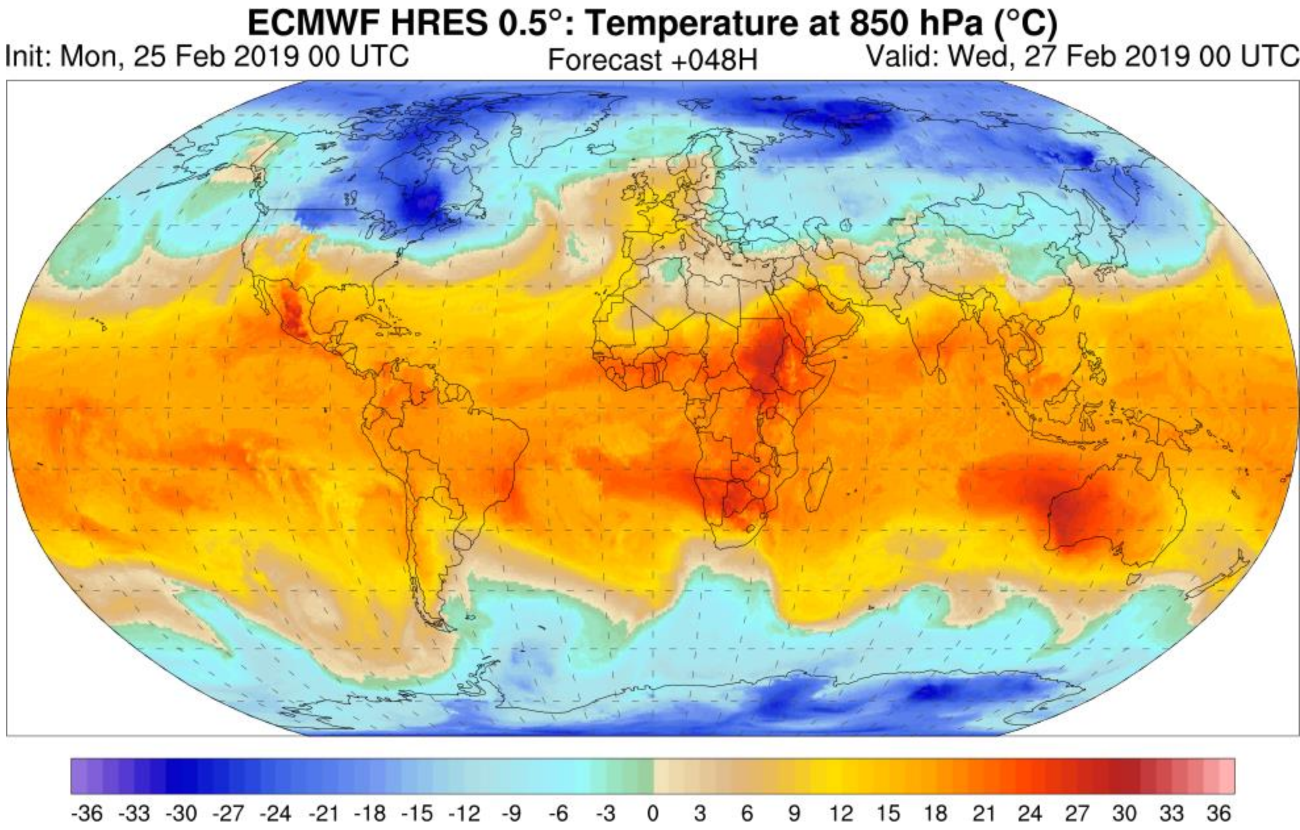
A multi billion dollar (hardware) industry

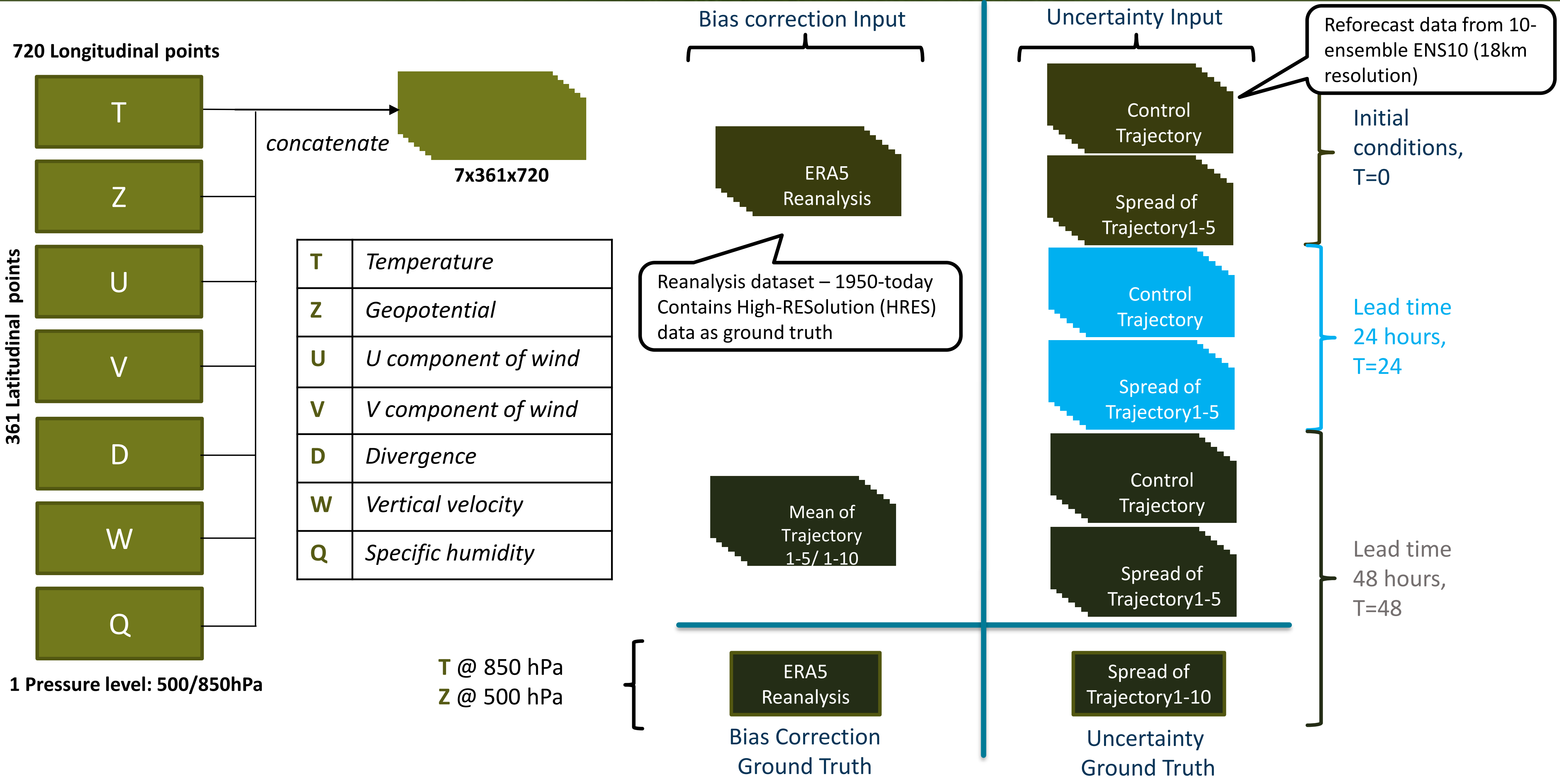
krtkl
Cambricon 寒武纪科技
Tachyum
adapteva
antmicro
SiFive
Tenstorrent
GRAPHCORE
BITMAIN
cerebras
another brain
thinci
KONIKU
GREENWAVE SYSTEMS
Kneron
KNOWM
LIGHTMATTER
PEZY Computing
LIGHTELLIGENCE
AMD
HUAWEI
Google
NVIDIA
Qualcomm
IBM

intel Nervana
SambaNova SYSTEMS
MYTHIC
TERADEEP
KALRAY
Think Force
NOVUMIND
AMPERE
gyrfalcon technology
Esperanto TECHNOLOGIES
GREENWAVES TECHNOLOGIES
WAVE COMPUTING
ChipIntelli
DEEPVISION
groq
DEEPSCALE
brainchip The Neuromorphic Computing Company

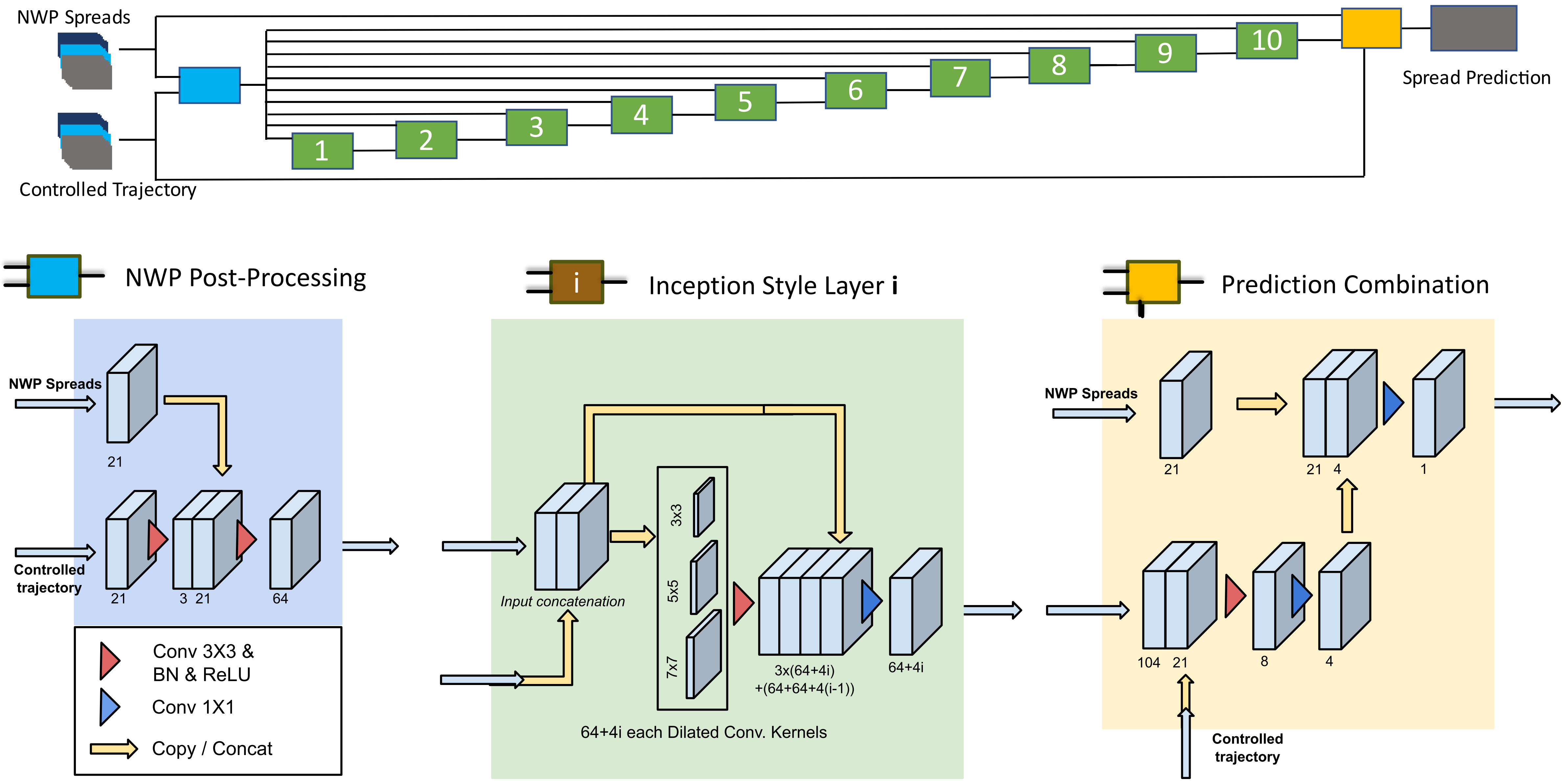
Data Acquisition: Data Selection

- **Spatial:**
  - 10-member ensembles from ECMWF's hindcasts “ENS10” and “ERA5” reanalysis data – both interpolated on lat/lon grid with 0.5 degree resolution
  - 850 hPa (T850) and 500 hPa (Z500) pressure levels
- **Temporal:**
  - Forecasts available from 0600 and 1800 UTC for each day from 2000-2018
  - Using smallest timestep: 3 hour steps

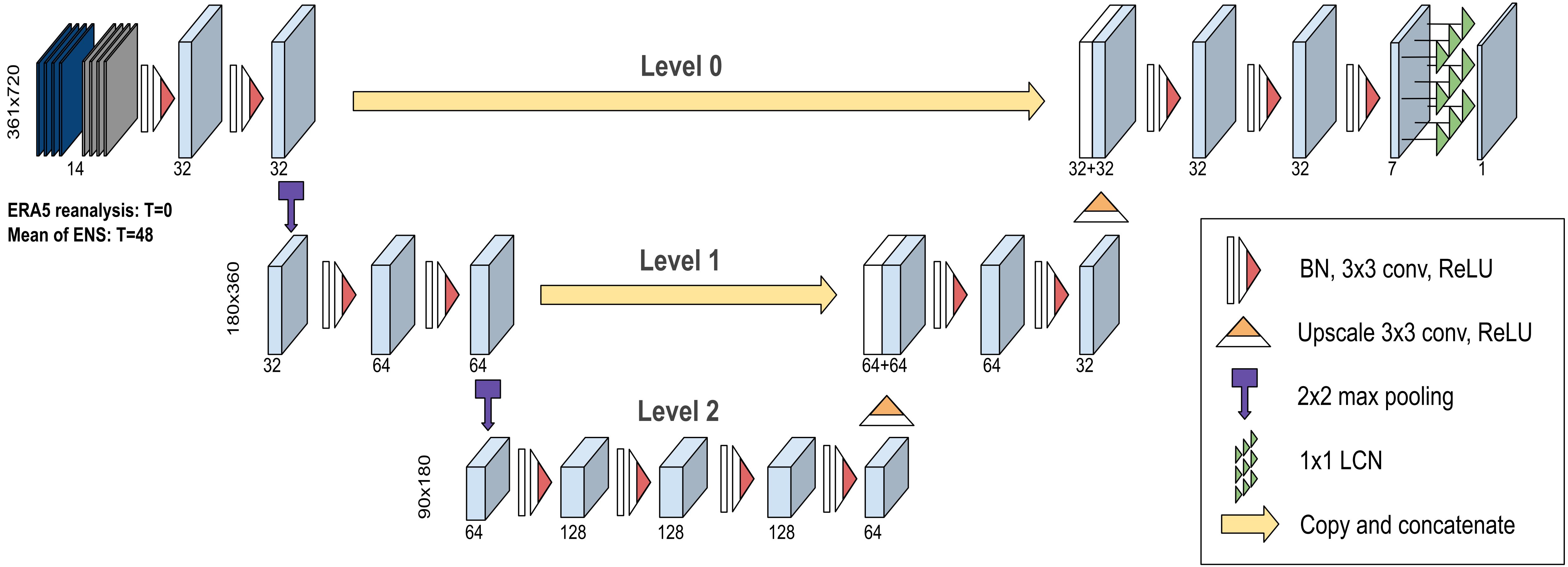



720 Longitudinal points
361 Latitudinal points
T
Z
U
V
D
W
Q
1 Pressure level: 500/850hPa
concatenate
7x361x720
T Temperature
Z Geopotential
U U component of wind
V V component of wind
D Divergence
W Vertical velocity
Q Specific humidity
T @ 850 hPa
Z @ 500 hPa
Bias correction Input
ERA5 Reanalysis
Reanalysis dataset – 1950-today
Contains High-RESolution (HRES) data as ground truth
Mean of Trajectory 1-5/ 1-10
ERA5 Reanalysis
Bias Correction Ground Truth
Uncertainty Input
Reforecast data from 10-ensemble ENS10 (18km resolution)
Control Trajectory
Spread of Trajectory1-5
Initial conditions, T=0
Control Trajectory
Spread of Trajectory1-5
Lead time 24 hours, T=24
Control Trajectory
Spread of Trajectory1-5
Lead time 48 hours, T=48
Spread of Trajectory1-10
Uncertainty Ground Truth

Uncertainty Quantification Network (based on ResNet)



Bias Correction Network (based on 3D-Unet + LCN)



Training: Setup

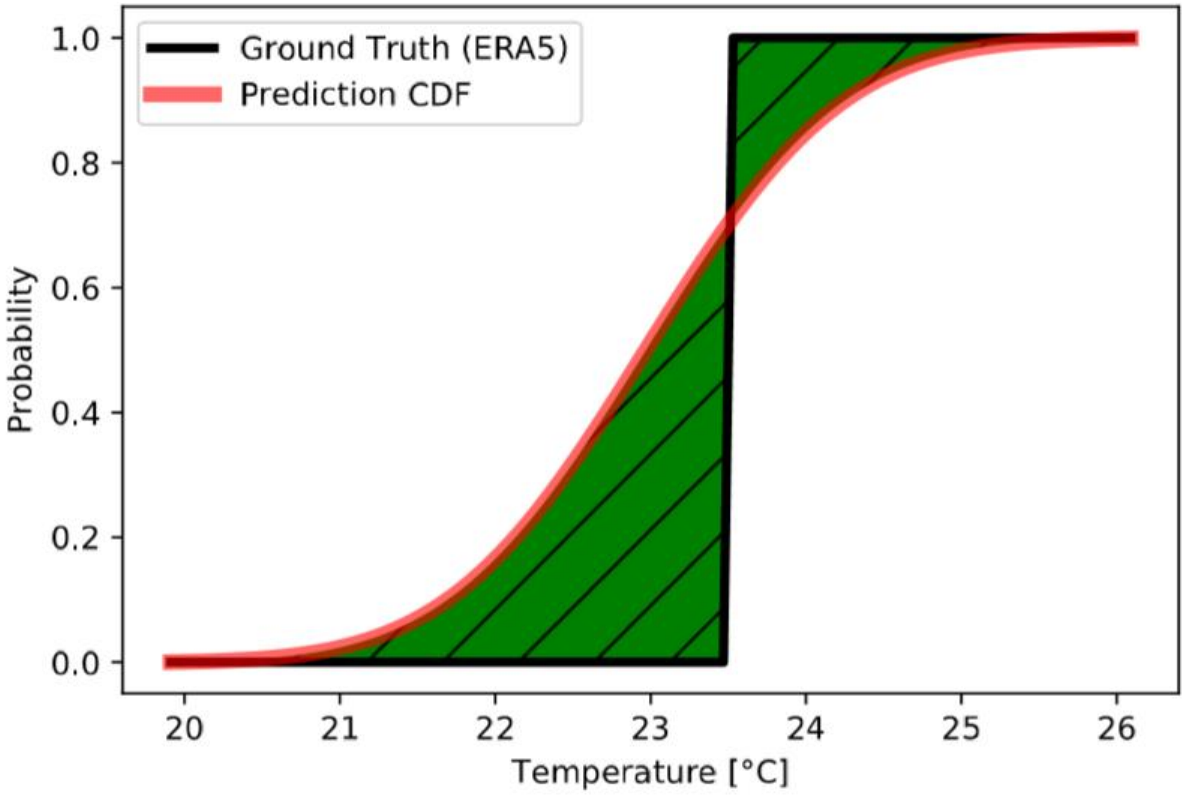
- **Framework**: TensorFlow
  - Default Adam optimizer
  - NVIDIA V100

    Four hours for training

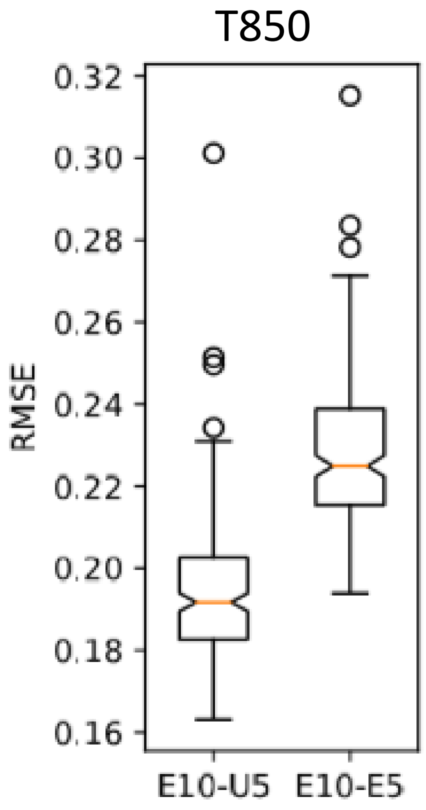
    1/3rd second for inference
  - Batch size 2

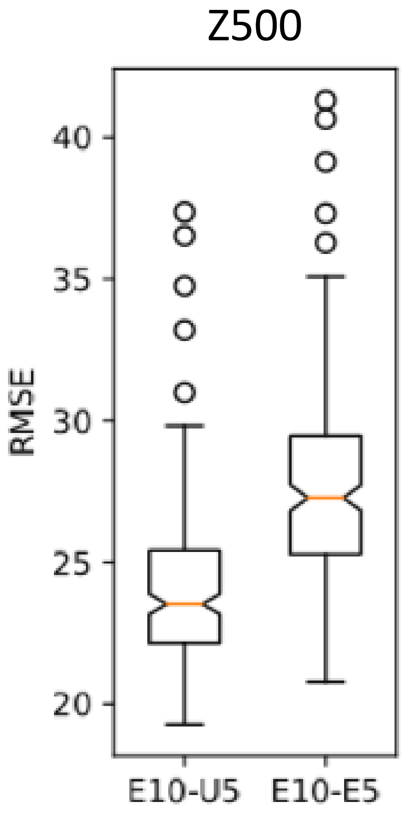
- **Training Loss**: MSE
  - Evaluation on RMSE

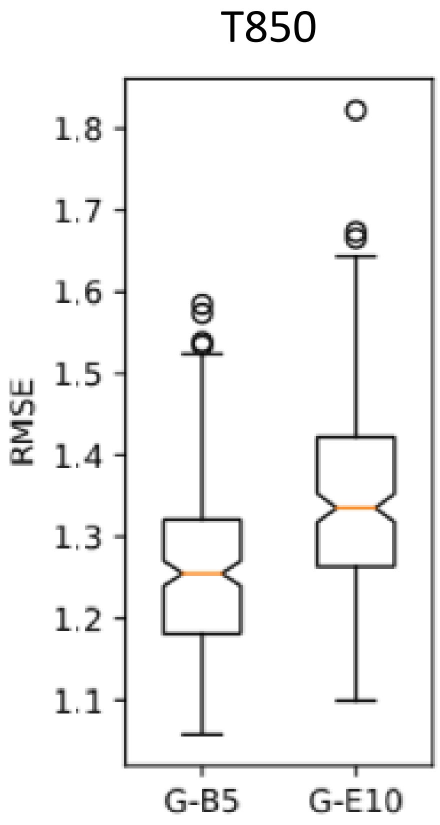
- **Combined training of both models**
  - Loss function $\mathrm{CRPS}(F, y) = \int_{-\infty}^{\infty} [F(x) - \mathbf{1}_{x>y}]^2 dx$

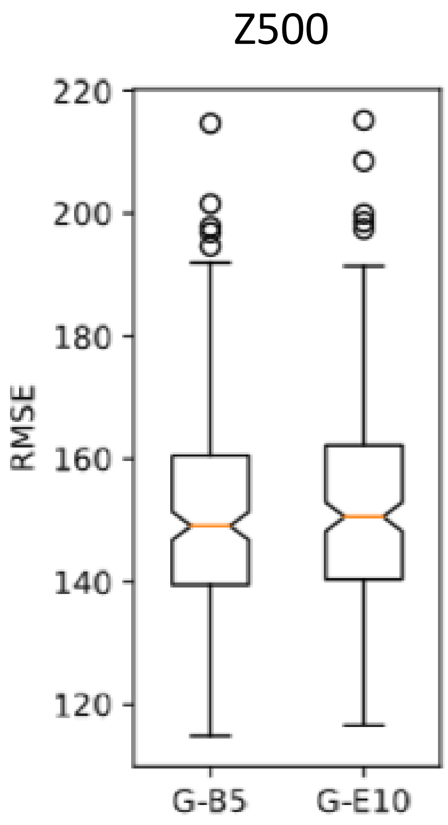


Global RMSE results









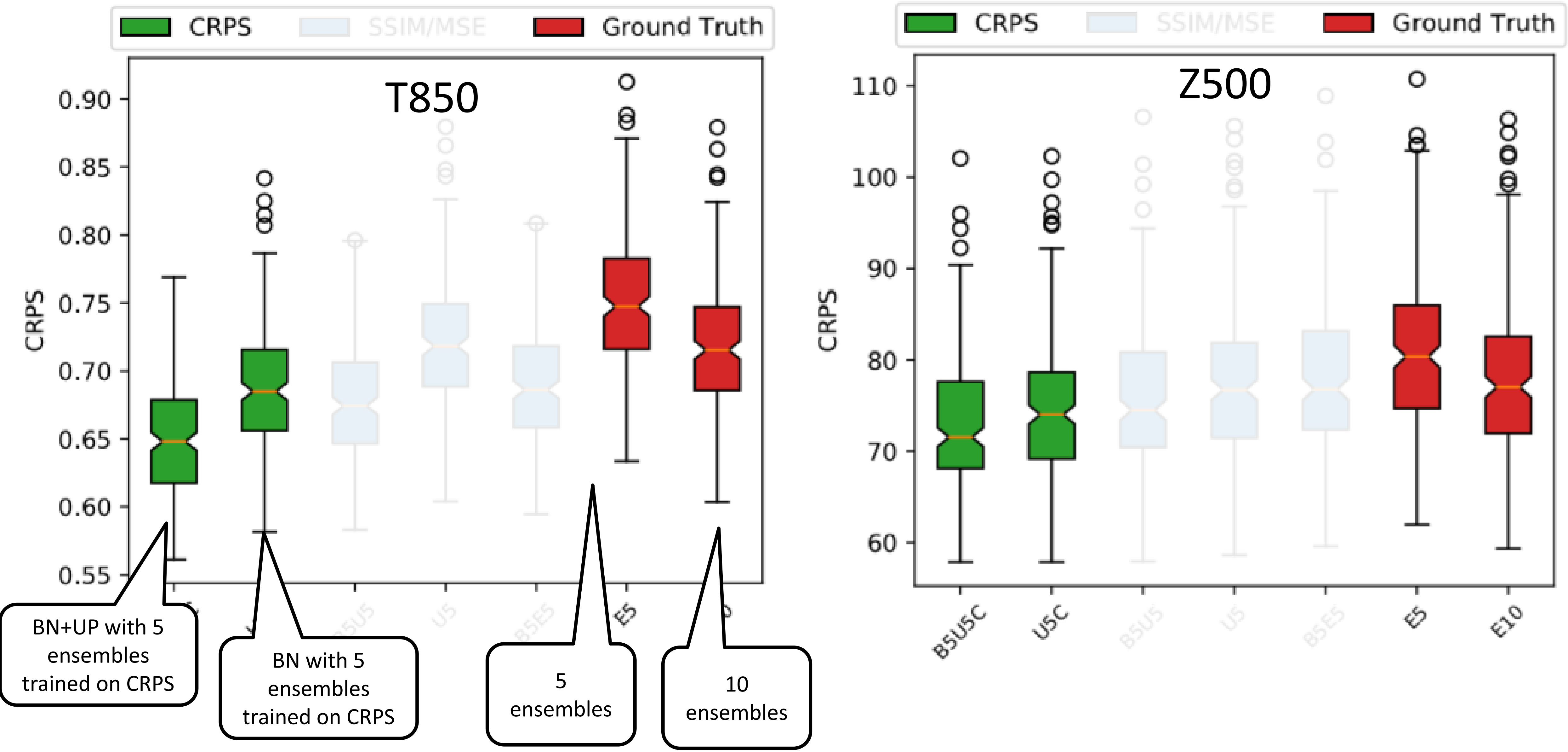
10 ensembles vs. UP with 5 ensembles

10 ensembles vs. 5 ensembles

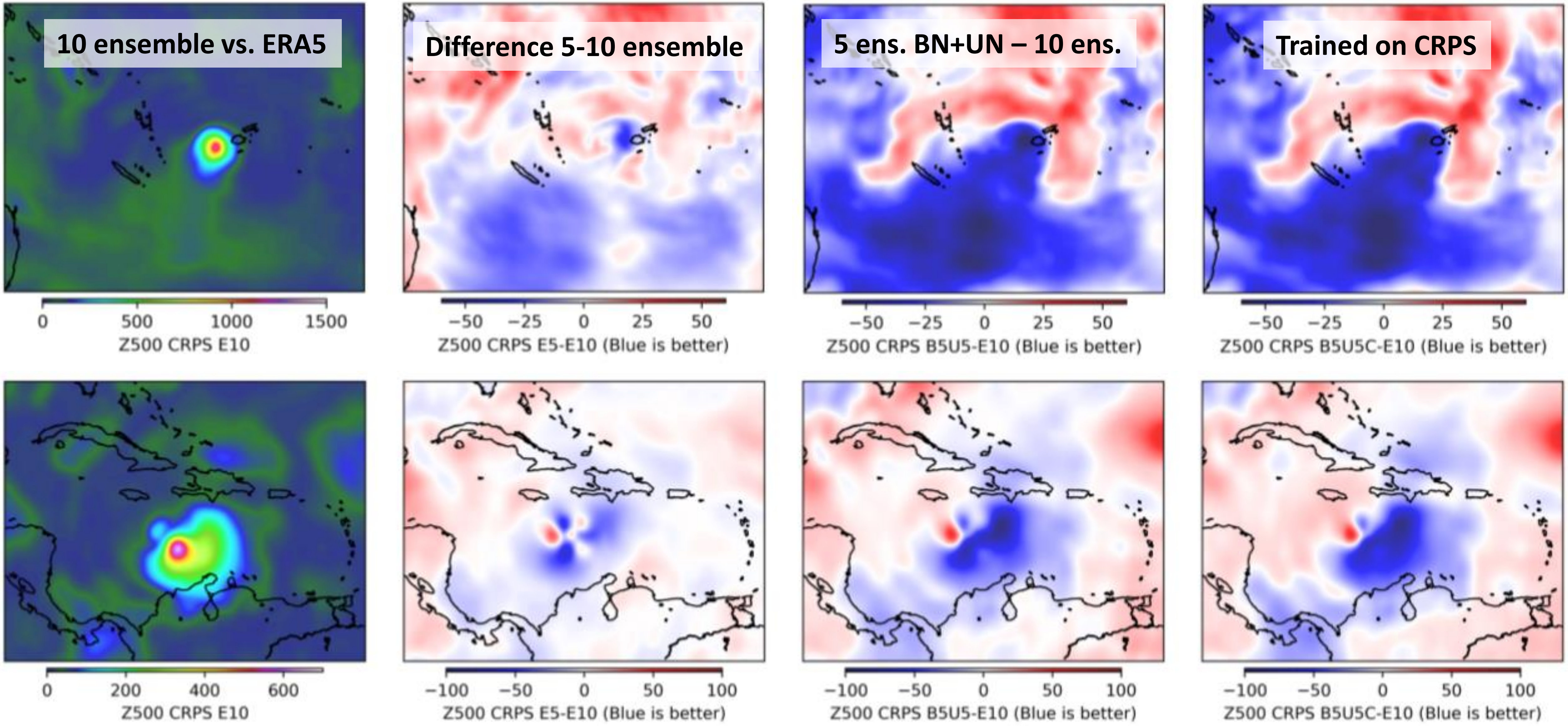
ERA5 (ground truth) vs. BN with 5 trajectories

ERA5 (ground truth) vs. 10 trajectories

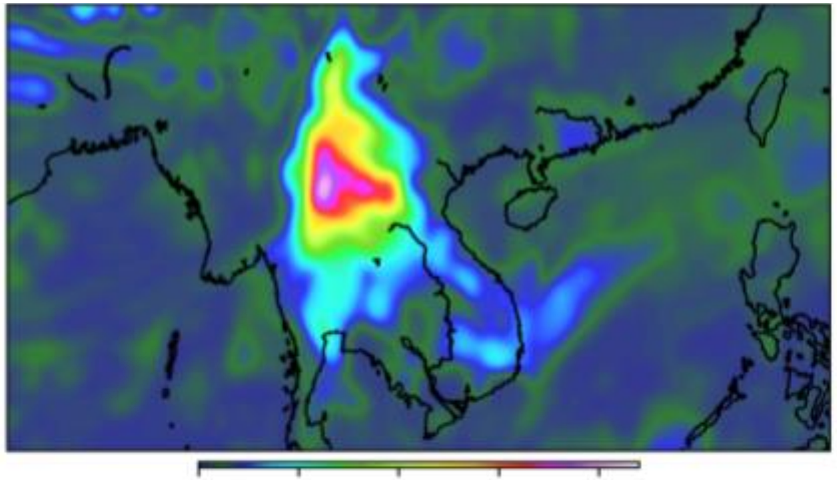
Global average values for each day 2016-2017)



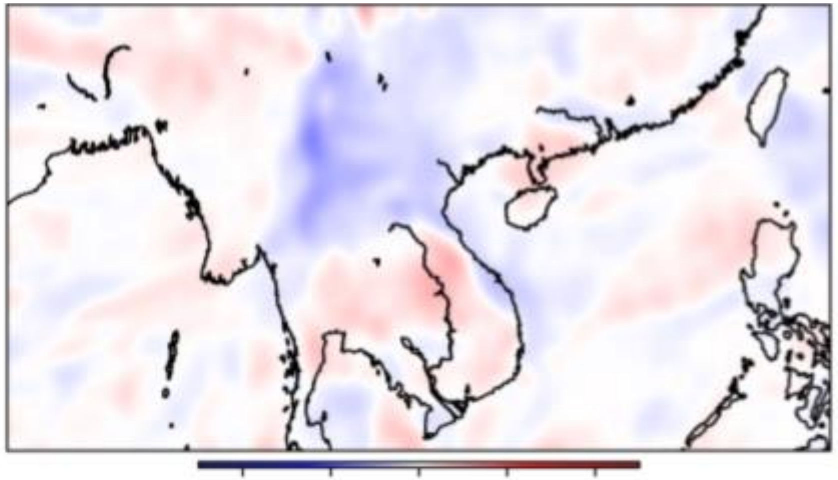
Extreme event: Tropical Cyclone Winston & Hurricane Matthews



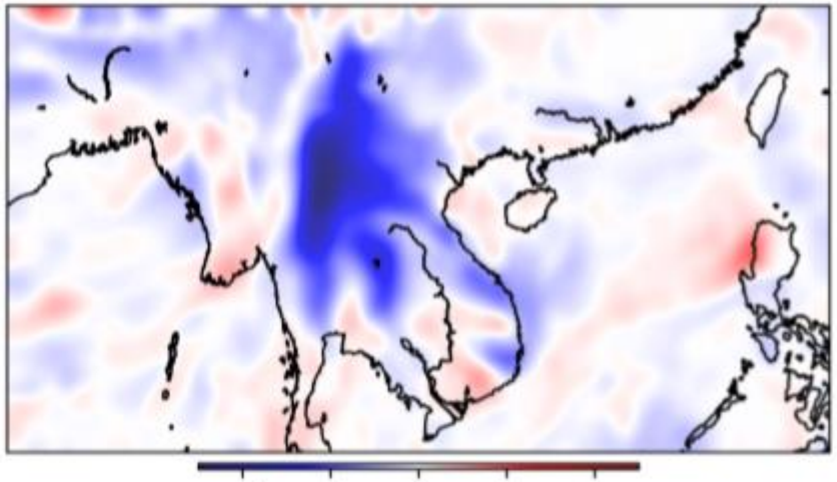
Cold wave over Asia

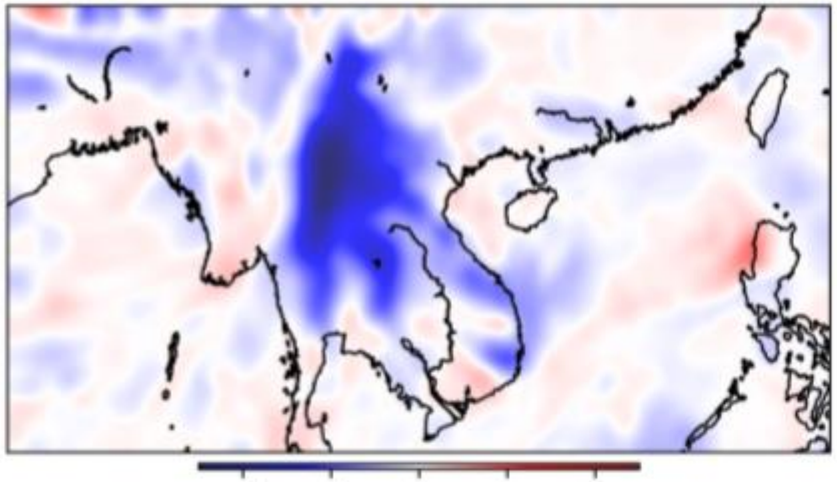


(a) E10

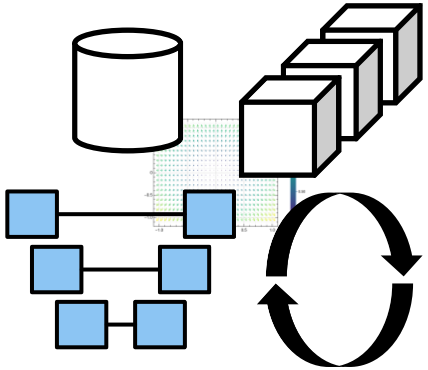


(b) E5-E10





Summary of our preliminary study



- Simple Deep Learning can be used to accelerate forecast pipelines
  - Take advantage of industry efforts to tune hardware and tool-chains
  - An informed approach is **necessary** to ensure improved results
- Using Encoder-Decoder networks for predicting mean and StdDev in ensemble systems yields higher accuracy than using small ensemble statistics
  - Fewer than half of the ensemble members are necessary
  - Accuracy improved with custom operators
- Promising for increasing performance in large-scale settings
  - Needs further investigation!
  - Join us/try yourself: https://github.com/spcl/deep-weather
- Future directions:
  - Larger datasets
  - Custom neural architectures for unstructured grids
  - Integrate into dace tool-chain for further optimization