

# Adapting Smart Dynamic Casting to Thin Folded Geometries

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**National Centre of Competence  
in Research  
Digital Fabrication**

# Adapting Smart Dynamic Casting to Thin Folded Geometries

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NCCR Digital Fabrication

Collaboration between Gramazio Kohler Research and the group of Physical Chemistry of Building Materials

# Adapting Smart Dynamic Casting to Thin Folded Geometries

- **Introduction**
- **Slipforming process model**
- **Material adjustments**
- **Conclusion and outlook**

# Introduction



*Mühlimatt Sports Centre, Studio Vacchini Architetti, 2010*



# Smart Dynamic Casting

- Robotic slipforming prefabrication
- Formwork moved along a digital trajectory
- Shaping the concrete

*Smart Dynamic Casting production for the DFAB house,  
Gramazio Kohler Research, ETH Zürich*

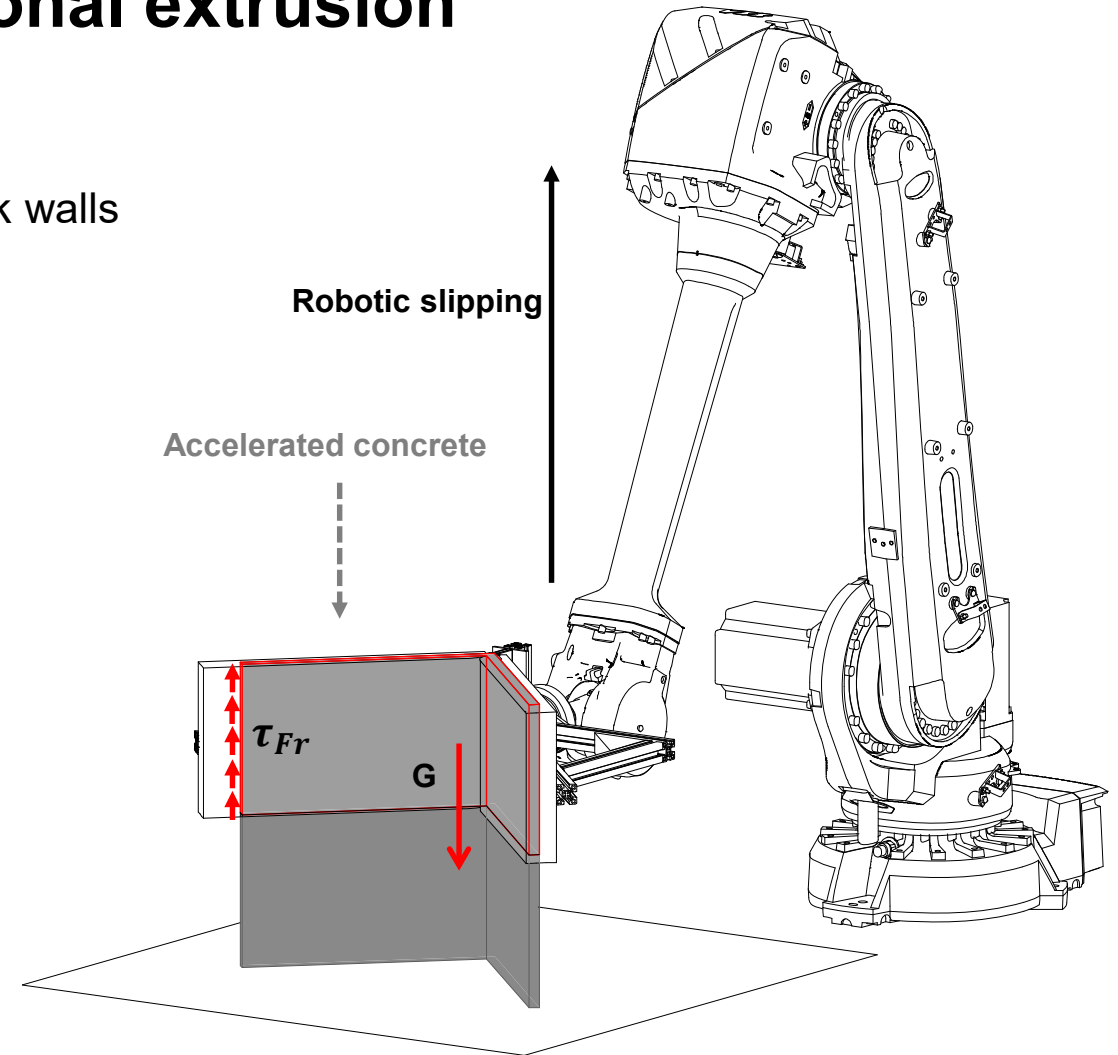
Gramazio Kohler Research 5  
ETH Zurich



# Smart Dynamic Casting

# Slipforming process model – gravitational extrusion

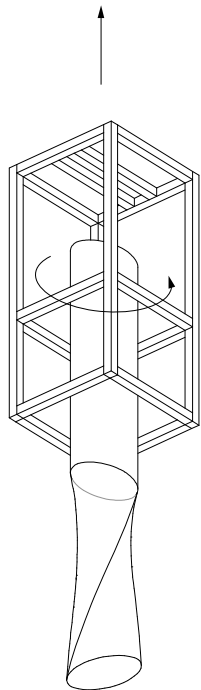
weight of concrete in the formwork <-> friction along the formwork walls



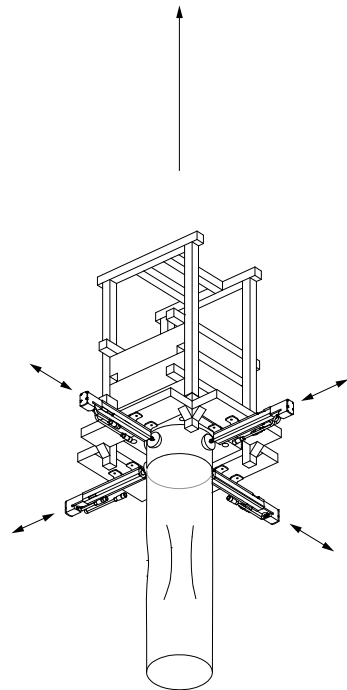


# Slipforming process model – formworks

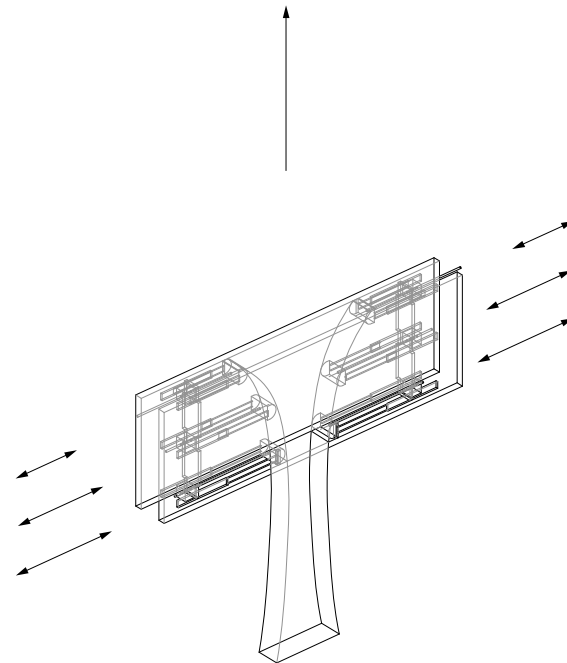
weight of concrete in the formwork  $\leftrightarrow$  friction along the formwork walls



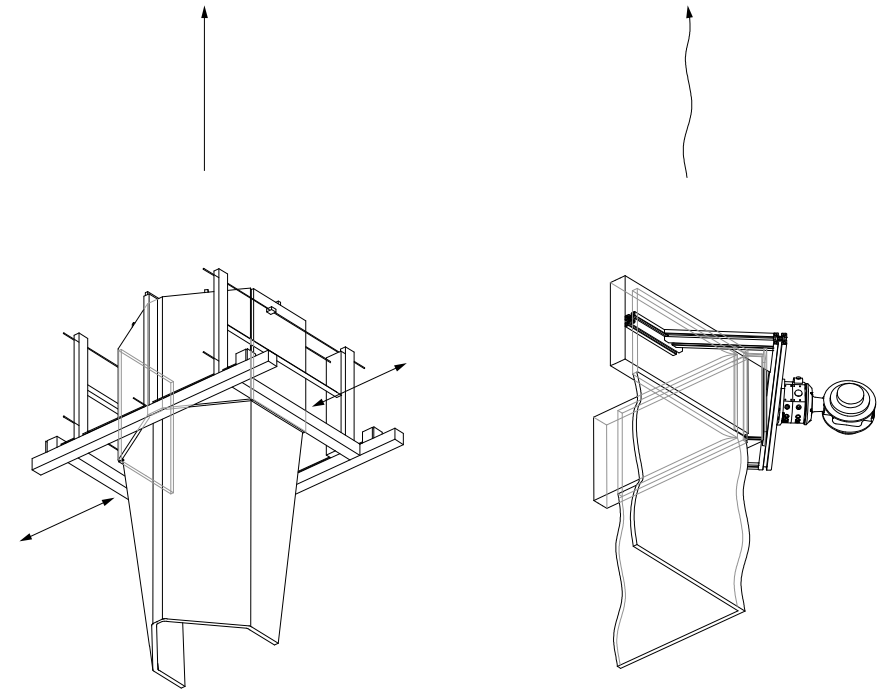
SDC Columns



SDC Mullions



SDC Thin-walled





SDC Columns



SDC Mullions



SDC Thin-walled



# Slipforming process model – formworks

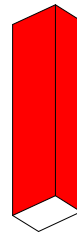
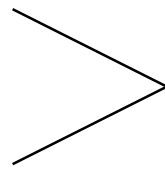
Slipforming as gravitational extrusion: weight of concrete in the formwork <-> friction along the formwork walls

Differences in hydrodynamic radius

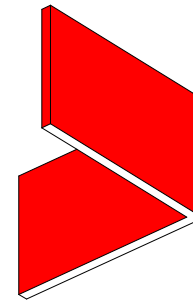
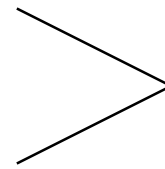
$$r_{hy} = \frac{2 \cdot Volume}{Surface}$$



$$r_{hy,columns} = 75\text{mm}$$



$$r_{hy,mullions} = 41\text{mm}$$



$$r_{hy,folded} = 25\text{mm}$$

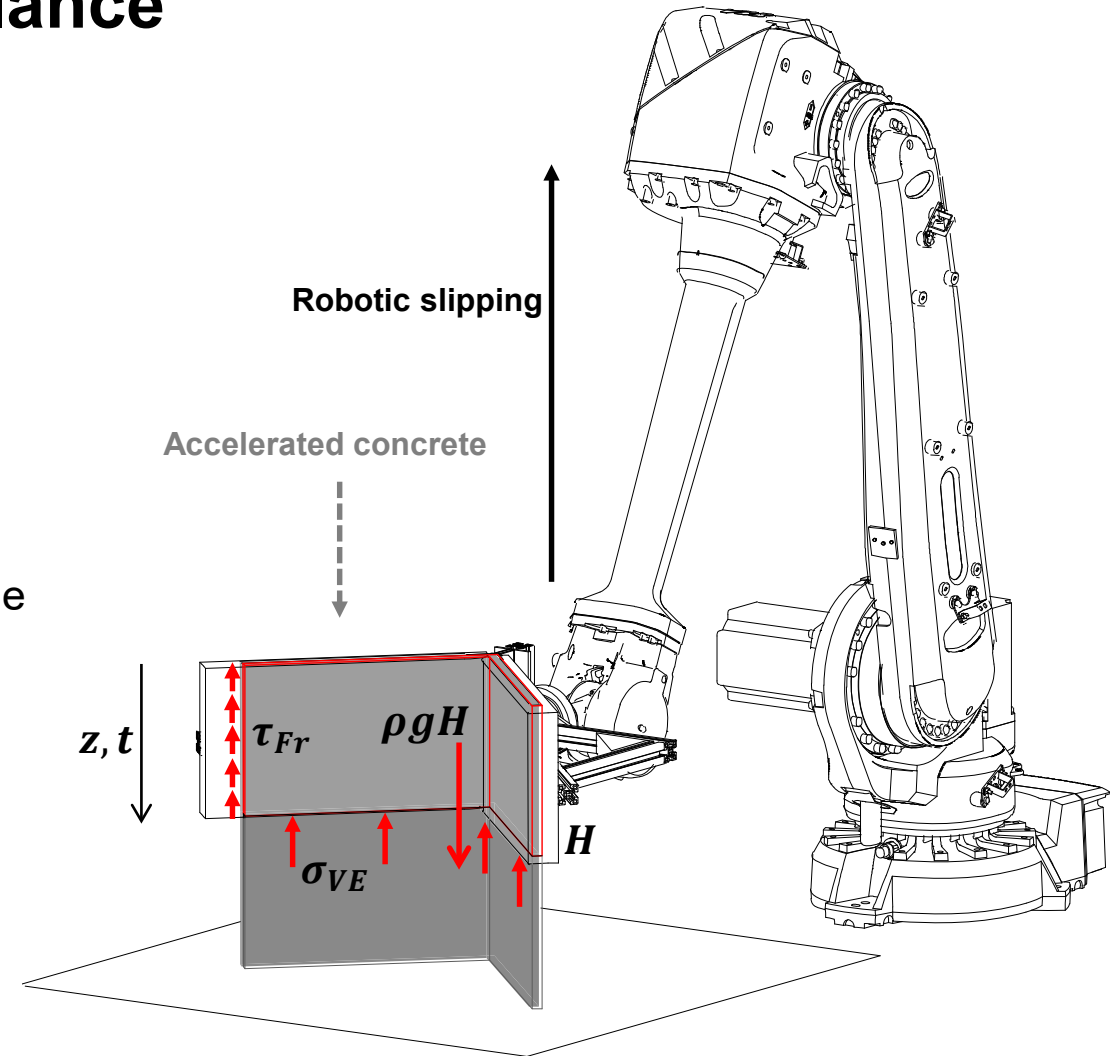
# Slipforming process model – force balance

Force balance in the formwork:

$$\sigma_{VE} = \rho g H - \frac{2}{r_{hy}} \int_0^z \tau_{Fr}(z) dz$$

- Friction  $\tau_{Fr}(t)$  is proportional to the yield stress
- Yield stress evolves according to a power law scaling over time

$$\tau_{Fr}(t) = \alpha_{Fr} \tau_0(t)$$



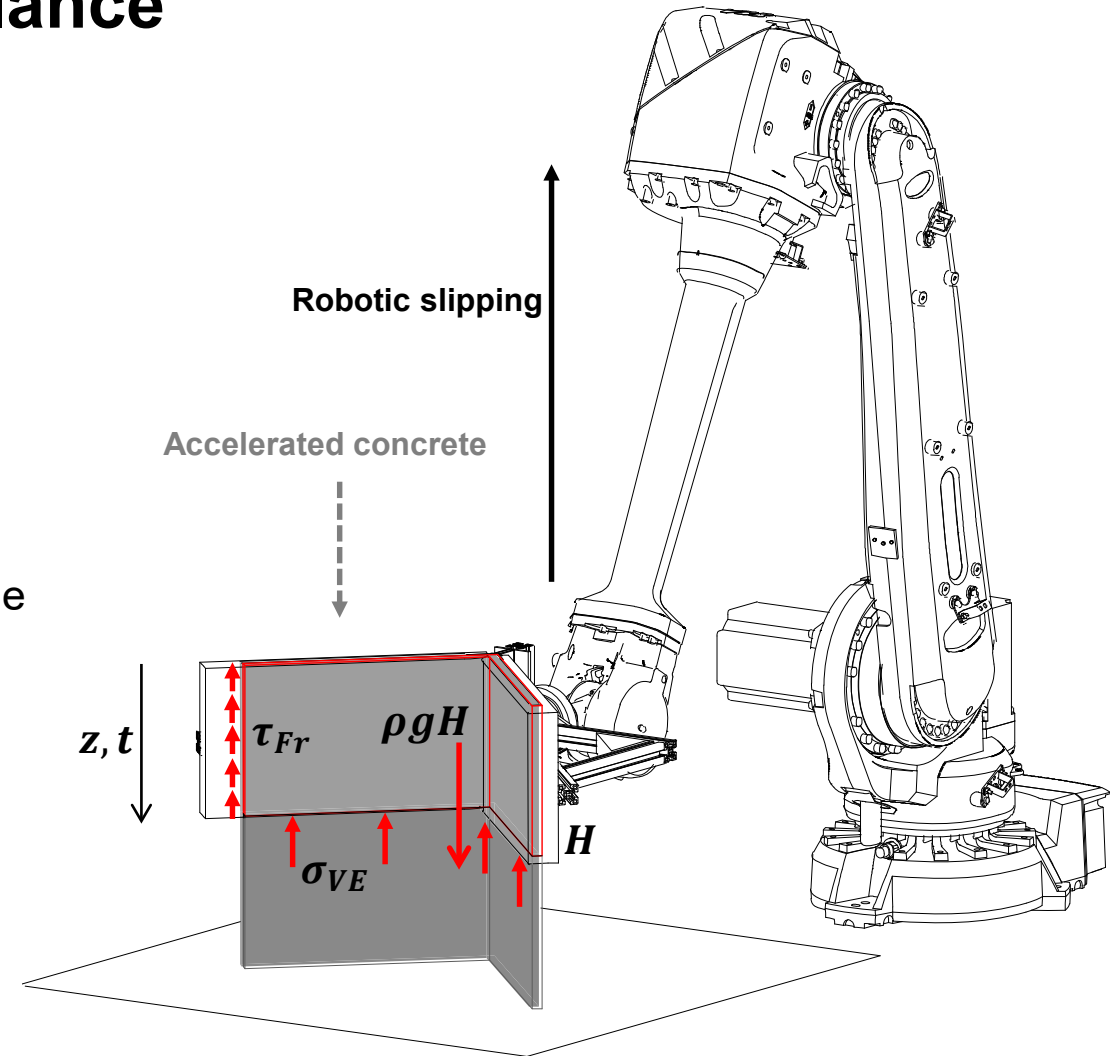
# Slipforming process model – force balance

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- Yield stress evolves according to a power law scaling over time

$$\tau_{Fr}(t) = \alpha_{Fr} \tau_0(t) = \alpha_{Fr} \alpha_C t^{\beta_C}$$



# Slipforming process model – force balance

Force balance:  $\sigma_{VE} = \rho g H - \frac{2}{r_{hy}} \int_0^z \tau_{Fr}(z) dz$       Friction force:  $\tau_{Fr}(t) = \alpha_{Fr} \tau_0(t) = \alpha_{Fr} \alpha_C t^{\beta_C}$

$$\sigma_{VE} = \rho g H - \frac{2}{r_{hy}} \int_0^{t_{Extr}} \tau_{Fr}(t) v dt$$

$$\sigma_{VE} = \rho g H - \frac{2v\alpha_{Fr}\alpha_C}{r_{hy}(1+\beta_C)} t_{Extr}^{1+\beta_C}$$

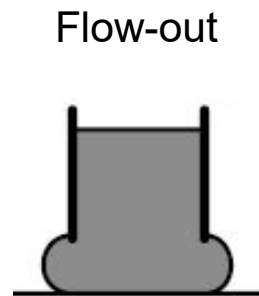
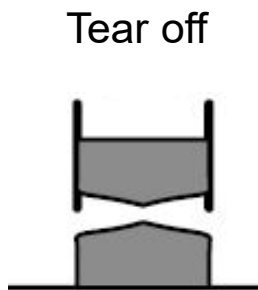
$$\sigma_{VE} = \rho g H - \boxed{\frac{H\alpha_{Fr}}{r_{hy}(1+\beta_C)}} \tau_0(t_{Extr})$$

**Global frictional parameter**

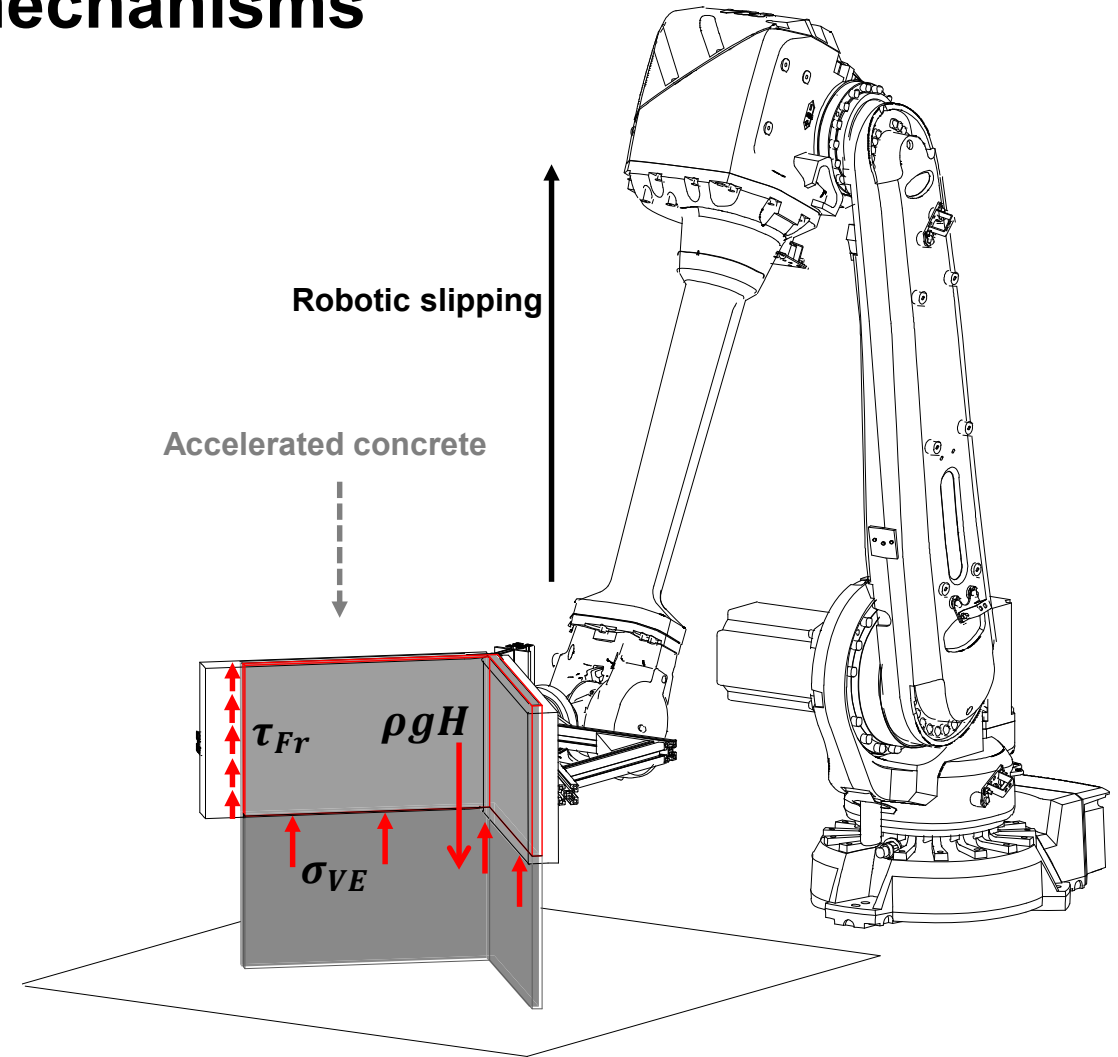
# Slipforming process model – failure mechanisms

Vertical stress  $\sigma_{VE}$  at the extrusion line:

- Positive
- Tresca criterion



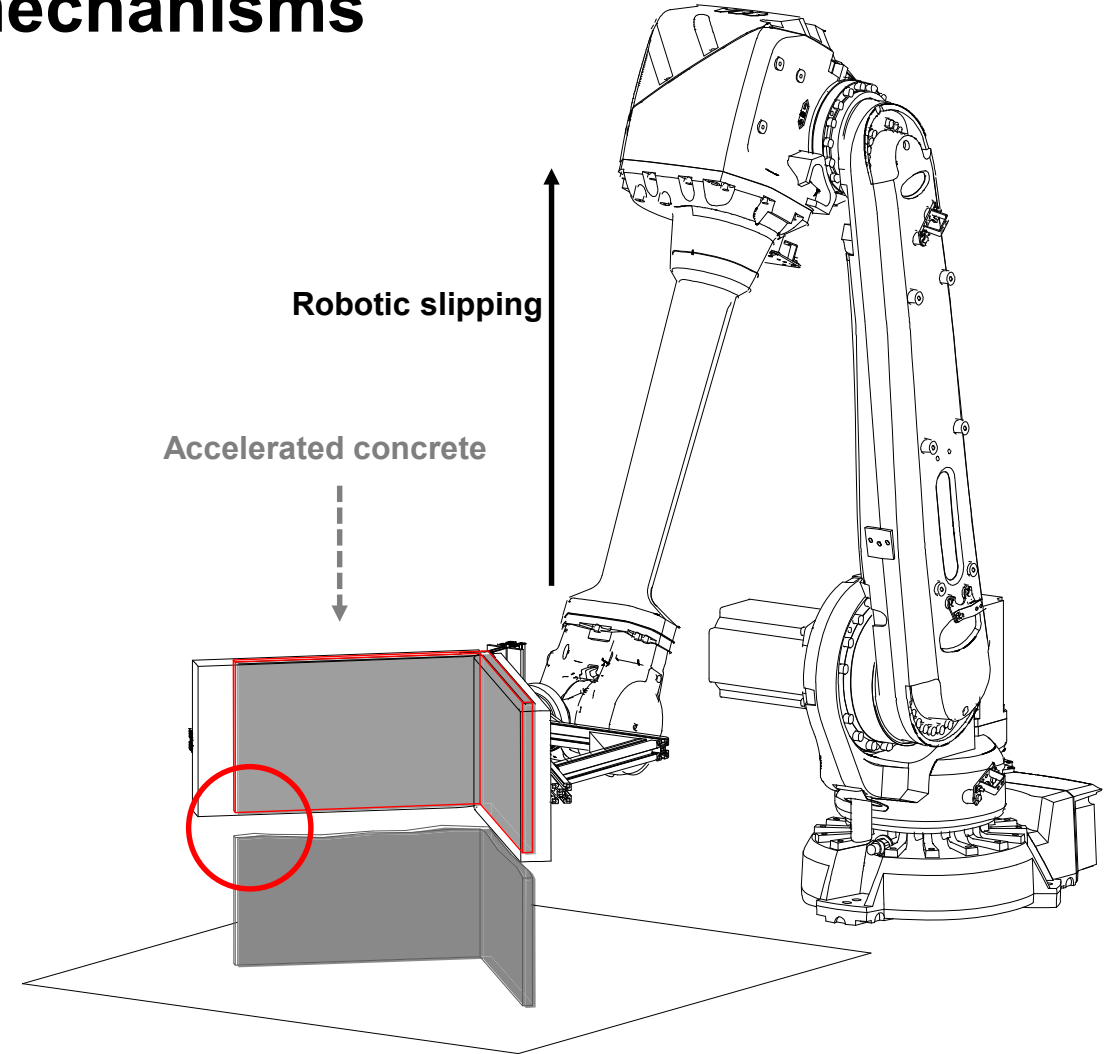
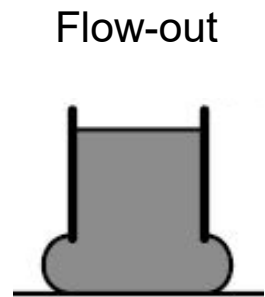
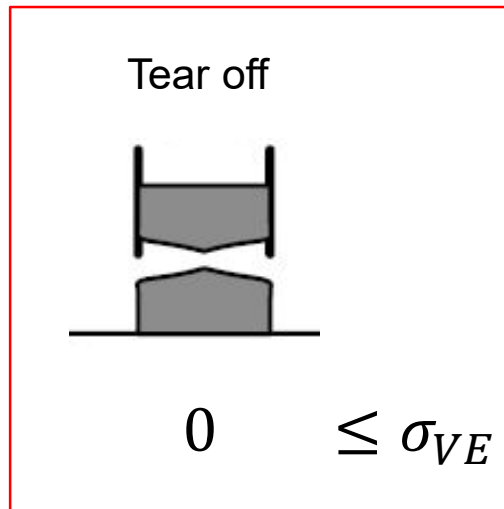
$$0 \leq \sigma_{VE} \leq 2\tau_0(t_{Extr})$$



# Slipforming process model – failure mechanisms

Vertical stress  $\sigma_{VE}$  at the extrusion line:

- Positive
- Tresca criterion

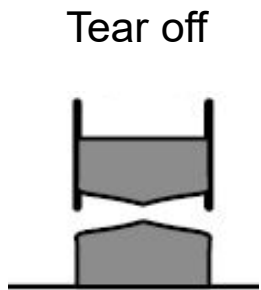




# Slipforming process model – failure mechanisms

Vertical stress  $\sigma_{VE}$  at the extrusion line:

- Positive
- Tresca criterion



Tear off

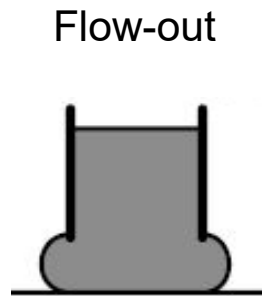
0

$\leq$

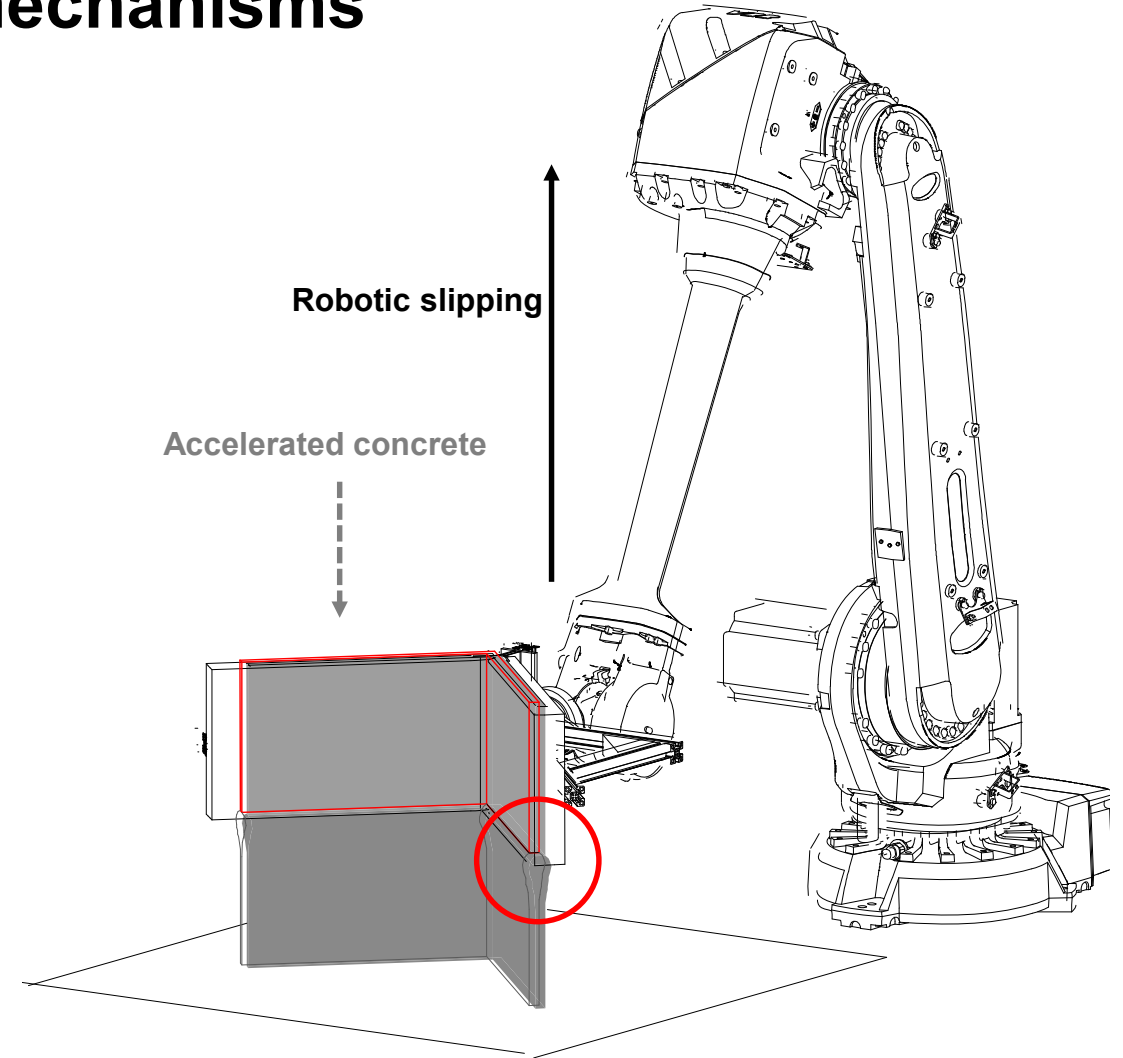
$\sigma_{VE}$

$\leq$

$2\tau_0(t_{Extr})$



Flow-out



# Slipforming process model – process window

Vertical stress:

$$\sigma_{VE} = \rho g H - \frac{H \alpha_{Fr}}{r_{hy}(1+\beta_C)} \tau_0(t_{Extr})$$

Failure criteria:

$$0 \leq \sigma_{VE} \leq 2 \tau_0(t_{Extr})$$

Process window:

$$\frac{H \alpha_{Fr}}{r_{hy}(1+\beta_C)} \leq \frac{\rho g H}{2 \tau_0(t_{Extr})} \leq 1 + \frac{H \alpha_{Fr}}{r_{hy}(1+\beta_C)}$$

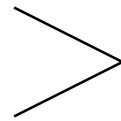
Global frictional parameter

# Slipforming process model – limits

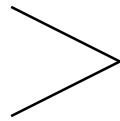
Process window: 
$$\frac{H\alpha_{Fr}}{r_{hy}(1+\beta_C)} \leq \frac{\rho g H}{2 \tau_0(t_{Extr})} \leq 1 + \frac{H\alpha_{Fr}}{r_{hy}(1+\beta_C)}$$

Negligible surface compared to volume

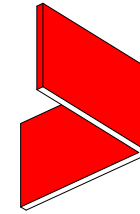
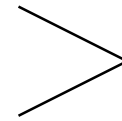
$$r_{hy} \rightarrow \infty$$



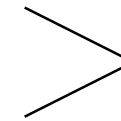
$$r_{hy,c} = 75\text{mm}$$



$$r_{hy,m} = 41\text{mm}$$



$$r_{hy,f} = 25\text{mm}$$



Negligible volume compared to surface

$$r_{hy} \rightarrow 0$$

$$0 \leq \frac{\rho g H}{2 \tau_0(t_{Extr})} \leq 1$$

$$\infty \leq \frac{\rho g H}{2 \tau_0(t_{Extr})} \leq \infty$$

Only sufficient strength required



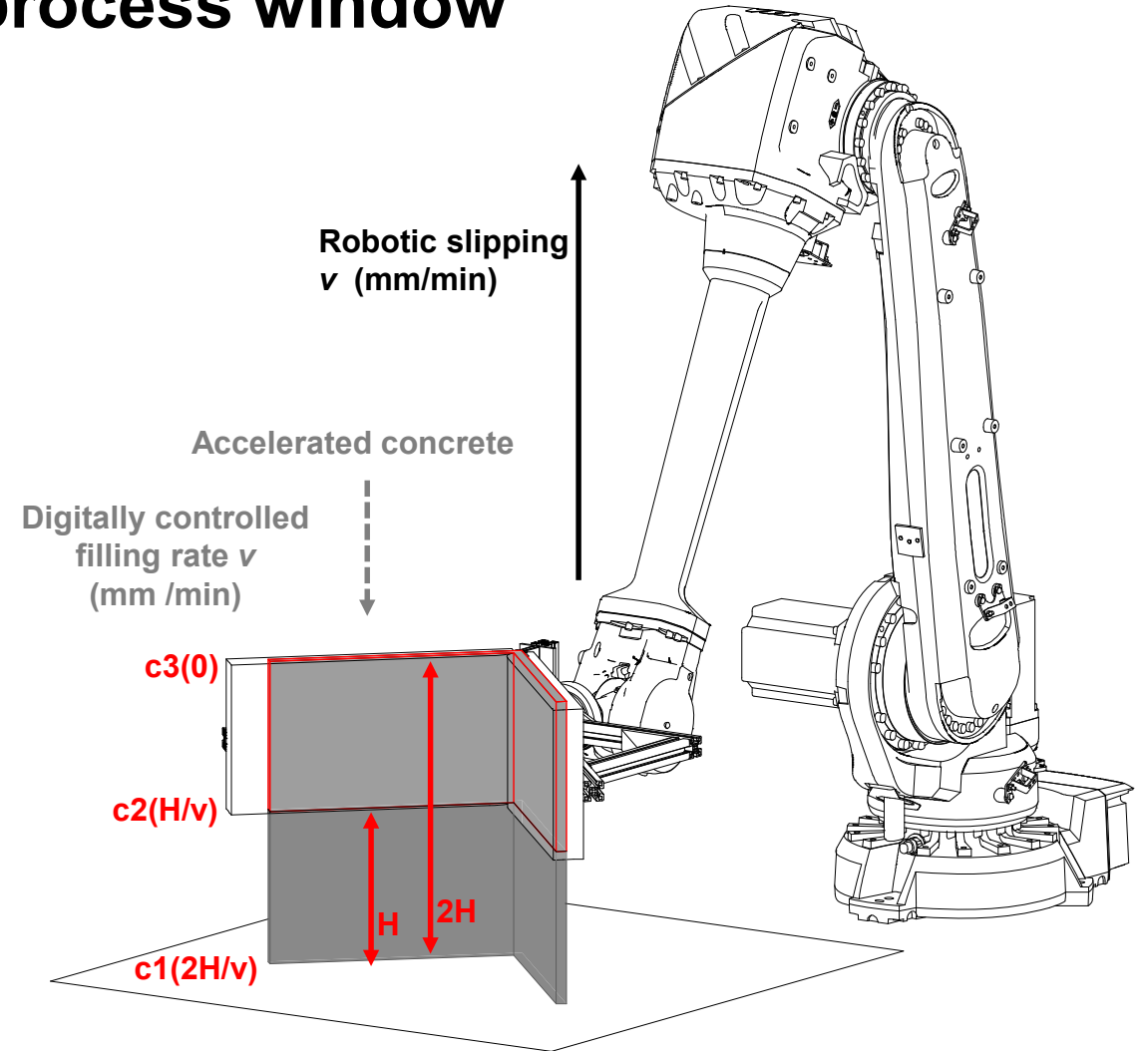
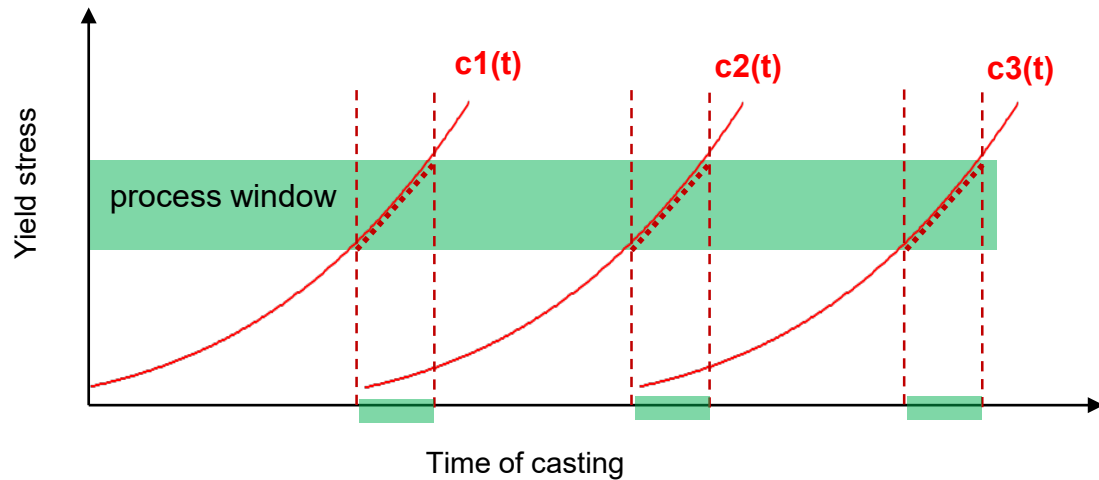
Process impossible!

# Results with empirical approach

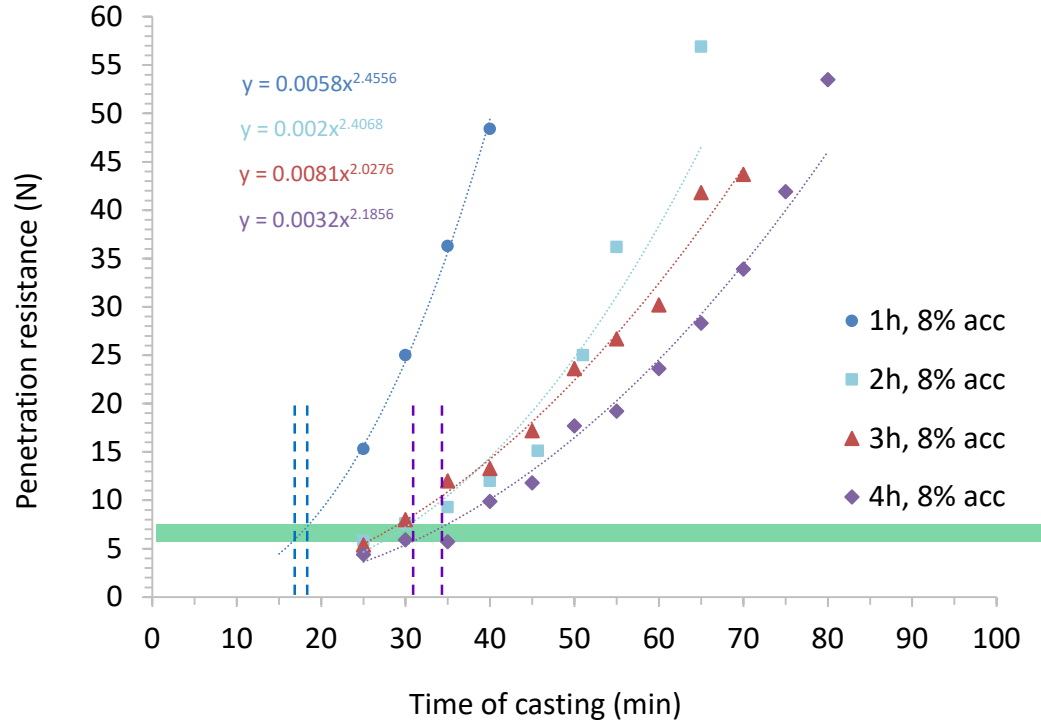


# Material requirements with narrow process window

- Uniform yield stress evolution over time
- Low slope in process window
- Extended time with target yield stress



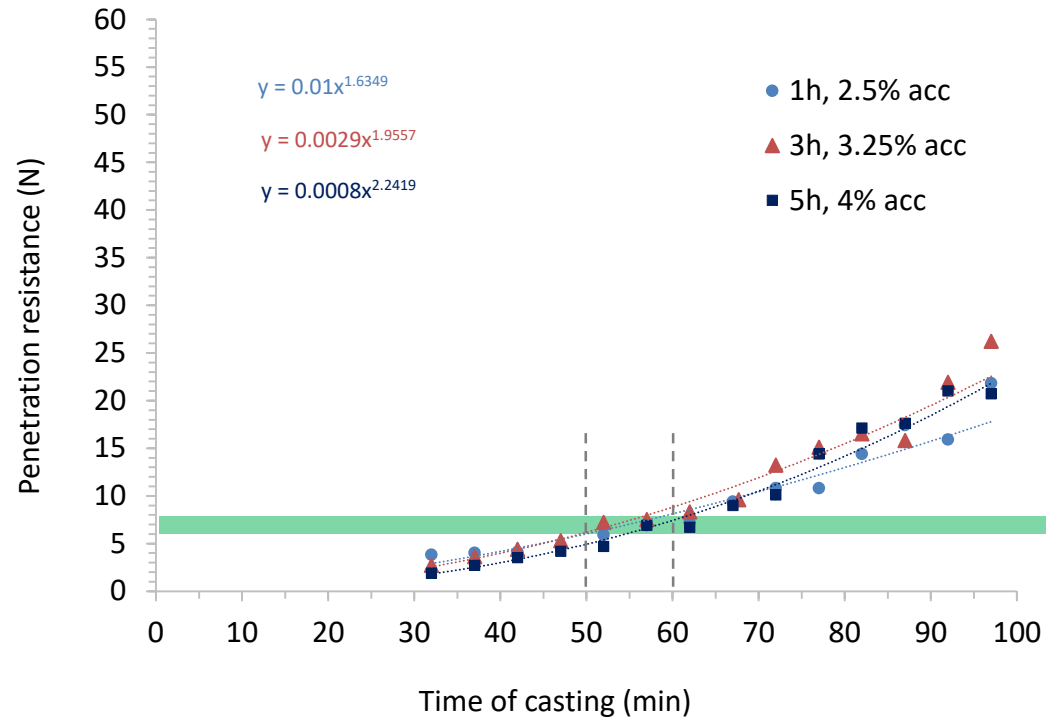
# Material adjustments



SDC\_NEST Mix



# Material adjustments



SDC FoldedStructures\_1 Mix







# Conclusion and outlook

- Folded structures are underused
- Theoretical slipforming process model with mathematical basis instead of fully empirical approach
- The process window for thin folded structures is smaller than in previous SDC experiments
- Material adjustments were necessary to overcome the processing difficulties
- The adjusted composition and processing were validated by robotic experiments

Further improvements:

- Online feedback for the slipping process
- Changes affecting the global parameter for friction

$$\frac{H\alpha_{Fr}}{r_{hy}(1+\beta_c)}$$



Thank you for your attention!

