## **ETH** zürich

## Introducing the Pedestrian Accessibility Tool (PAT) Open source GIS-based walkability analysis

**Conference Paper** 

Author(s): Erath, Alexander; van Eggermond, Michael A.B.; Ordonez Medina, Sergio Arturo (); Axhausen, Kay W. ()

Publication date: 2017

Permanent link: https://doi.org/10.3929/ethz-b-000207177

Rights / license: In Copyright - Non-Commercial Use Permitted Thanks for the kind notice.

I would like to clarify the accepted version option. I uploaded the final version that was not edited by the Journal committee. The Journal does some final changes. As far as I know, the Jornal of Field Robotics is fine with uploading the final submitted version before the formatting by the Jornal. I might made a mistake and in this case I should change the version of the upload.

Thanks!

Marko

On 11.06.20 07:20, ETH Research Collection wrote:

Dear Mr Bjelonic,

Thank you for the *accepted version* of your journal article in <u>https://www.research-collection.ethz.ch/handle/20.500.11850/419575</u>.

Please note that the journal issue cannot yet be accessed as the publisher's DOI <u>https://doi.org/10.1002/rob.21974</u> does not resolve. Furthermore, the publisher requires a 12 months' embargo period for <u>accepted versions</u>, please refer also to <u>http://sherpa.ac.uk/romeo/issn/1556-4959/</u>.

Should you need any further information, please do contact our team.

Yours sincerely, Research Collection

Françoise Knüsel

ETH Zurich, ETH Library, E-Publishing1Research Collection, Rämistrasse 101, 8092 Zurich, phone +41 44 632 72 22, research-collection@library.ethz.ch, www.research-collection.ethz.ch

Coffee Lectures: Discover our new <u>bite-sized courses</u>, at 15.15 on Wednesday afternoons!

-----Ursprüngliche Nachricht-----Von: <u>research-collection@library.ethz.ch</u> <<u>research-collection@library.ethz.ch></u> Gesendet: 10. Juni 2020 16:40 An: ETH Research Collection <u><<u>research-collection@library.ethz.ch></u></u> Betreff: Research Collection: A new Journal Article with file was submitted.

A new Item was submitted into the repository:

Title: Perceptive Whole Body Planning for Multi-legged Robots in Confined Spaces

Author(s): Buchanan, Russell; Wellhausen, Lorenz; Bjelonic, Marko;
Bandyopadhyay, Tirthankar; Kottege, Navinda; Hutter, Marco
Submitter: Bjelonic, Marko (marko.bjelonic@mavt.ethz.ch)
URL: <a href="https://www.research-collection.ethz.ch/handle/20.500.11850/419575">https://www.research-collection.ethz.ch/handle/20.500.11850/419575</a>

--Marko Bjelonic ETH Zürich +41446322145 www.markobjelonic.com